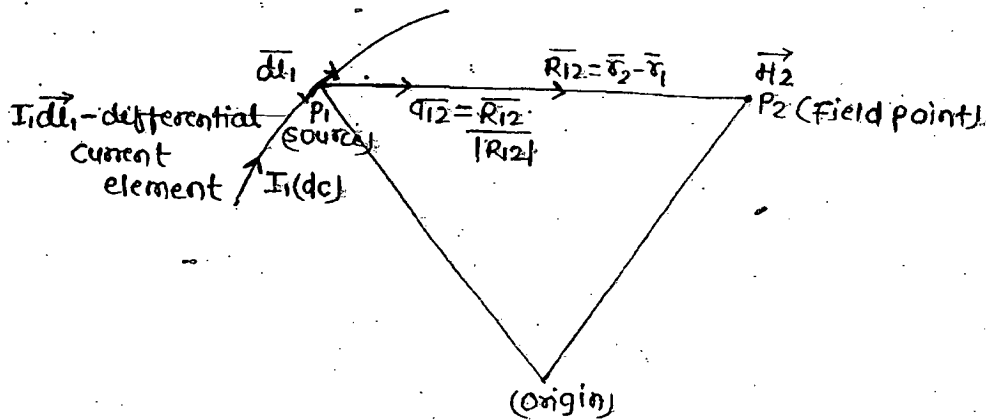


* Static Magnetic field $\rightarrow$ [Source $\rightarrow I(dc)$]

* Biot Savart law $\rightarrow$



* Magnetic Field intensity at point 2 (P_2) due to $I_1 d\vec{l}_1$ located at P_1 is

$$d\vec{H}_2 = \frac{I_1 d\vec{l}_1 \times \vec{a}_{12}}{4\pi |\vec{R}_{12}|^2} \text{ (Amp/m)}$$

* Total magnetic field intensity at P_2 is

$$\vec{H}_2 = \oint \frac{I_1 d\vec{l}_1 \times \vec{a}_{12}}{4\pi |\vec{R}_{12}|^2}$$

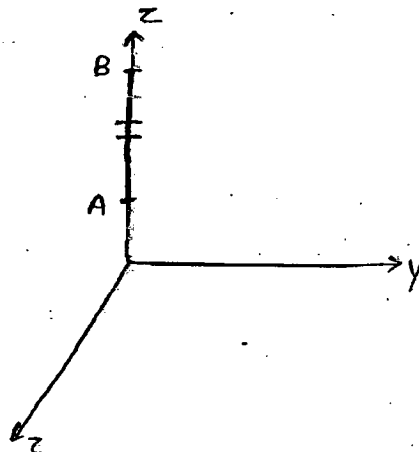
$\oint$ $\rightarrow$ current flow in closed loop

$$\vec{H}_2 = \oint \frac{I_1 d\vec{l}_1 \times \vec{R}_{12}}{4\pi |\vec{R}_{12}|^3}$$

$\vec{R}_{12}$ is unknown ($\vec{R}_{12}$) = field point - Source point

Que. $\rightarrow$ Find $\vec{H}$ in all the regions due to a finite long current line carrying $I(dc)$ current lying on the z -axis from point A to point B as shown

(derivation not req.)



Soln →

$$\vec{dM} = \frac{I d\vec{l}_1 \times \vec{R}_{12}}{4\pi |\vec{R}_{12}|^3}$$

$$\vec{dM} = \frac{I dz' q_z \times [s q_\phi + (z-z') q_z]}{4\pi (\sqrt{s^2 + (z-z')^2})^3}$$

$$\vec{dM} = \frac{I dz' [s q_\phi + 0_z]}{4\pi (\sqrt{s^2 + (z-z')^2})^3}$$

Total M field is

$$\vec{M} = \int_{z=A}^B \frac{I s dz'}{4\pi (\sqrt{s^2 + (z-z')^2})^3} q_\phi$$

Integration variable z' is in the denominator, so introduce angle terms.

$$\vec{M} = \int_{z=A}^B \frac{I s dz'}{4\pi |\vec{R}_{12}|^3} q_\phi$$

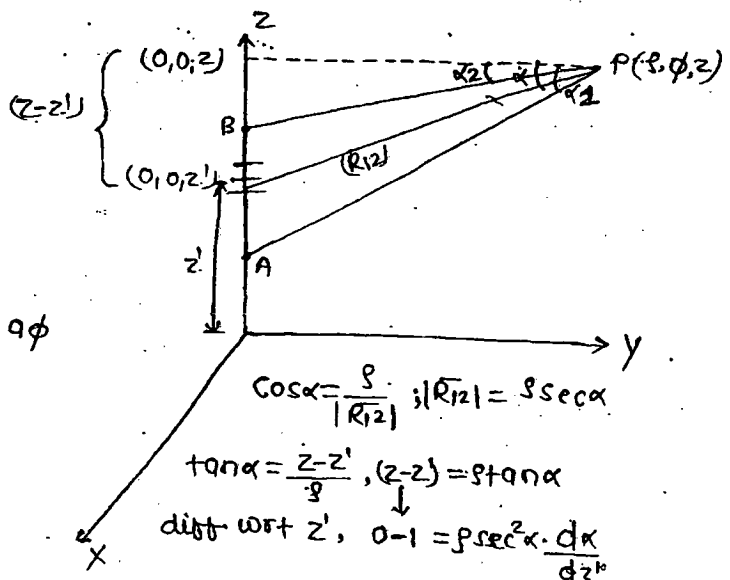
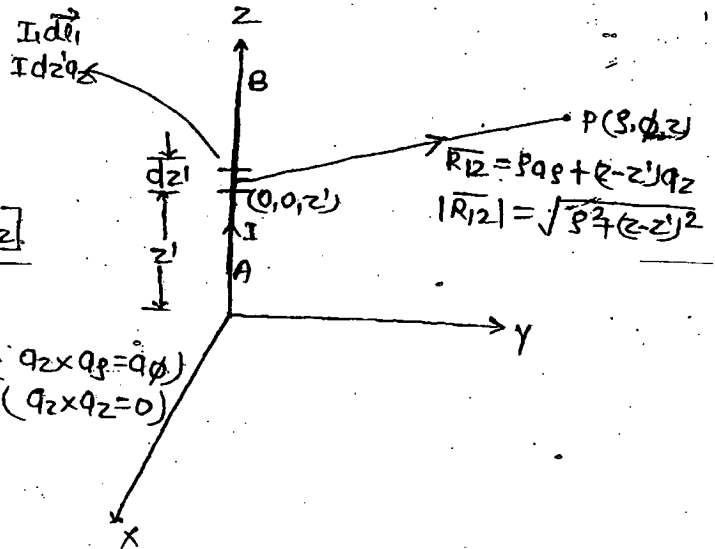
$$\vec{M} = \int_{z=A}^B \frac{s}{|\vec{R}_{12}|^2} dz' q_\phi$$

$$\vec{M} = \frac{I}{4\pi} \int_{\alpha=\alpha_1}^{\alpha_2} \frac{\cos \alpha}{s^2 \sec^2 \alpha} (-s \sec^2 \alpha d\alpha) q_\phi$$

$$\vec{M} = \frac{-I}{4\pi s} \int_{\alpha=\alpha_1}^{\alpha_2} \cos \alpha d\alpha \cdot q_\phi$$

$$\vec{M} = \frac{-I}{4\pi s} (\sin \alpha)_{\alpha=\alpha_1}^{\alpha_2} q_\phi$$

$$\vec{M} = \frac{I}{4\pi s} [-(\sin \alpha_2 - \sin \alpha_1)] q_\phi$$



$$\cos \alpha = \frac{s}{|\vec{R}_{12}|}, |\vec{R}_{12}| = s \sec \alpha$$

$$\tan \alpha = \frac{z-z'}{s}, (z-z') = s \tan \alpha$$

$$\text{dist wrt } z', 0-1 = s \sec^2 \alpha \cdot \frac{d\alpha}{dz'}$$

$$-dz' = s \sec^2 \alpha d\alpha$$

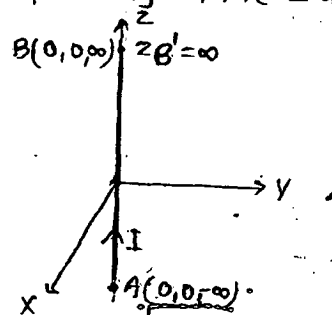
Case → Find $\vec{M}$ in all the regions due I(dc) current flowing on the z-axis

$$\tan \alpha = \frac{z-z'}{s}$$

$\alpha_1 \rightarrow$ angle of point A $(0,0,-\infty)$

$$\tan \alpha_1 = \frac{z-z'_A}{s} = \frac{z-(-\infty)}{s} = \infty = \tan \frac{\pi}{2}$$

$$\alpha_1 = \pi/2$$



$\alpha_2 \rightarrow$ Angle of point B(0,0, ∞)

$$\tan \alpha_2 = \frac{z-z'_B}{\rho} = \frac{z-(\infty)}{\rho} = -\infty = \tan^{-1}\left(\frac{-\pi}{2}\right)$$

$$\alpha_2 = -\frac{\pi}{2}$$

$$\vec{H} = \frac{I}{4\pi\rho} [-(-1-1) q\phi]$$

$$\vec{H} = \frac{I}{4\pi\rho} (2) q\phi$$

$$\vec{H} = \frac{I}{2\pi\rho} q\phi$$

Note $\rightarrow$ (1) $\vec{H}$ due to I(dc) flowing along z-axis is

$$\boxed{\vec{H} = \frac{I}{2\pi\rho} q\phi} \quad H \propto \frac{1}{\rho}$$

* For current along z-axis $\vec{H}$ values do not depend on ϕ, z

(2) $\vec{H}$ in all the regions due to Idc current flowing from A to B on z-axis is

$$\vec{H} = \frac{I}{4\pi\rho} [-(\sin\alpha_2 - \sin\alpha_1)] q_H$$

$$q_H = q_L \times q_{\perp} \text{ (}\perp\text{ perpendicular)}$$

$$q_H = \text{Unit vector in the dirn of } \vec{H}$$

$$q_L = \text{Unit vector in the dirn of current}$$

$$q_{\perp} = \text{Unit vector in the dirn of perpendicular line drawn from current line to field point}$$

* For current on the z-axis

$$\tan \alpha = \frac{z-z'}{\rho} = \frac{(z-z')}{\sqrt{x^2+y^2}}$$

For x-axis:-

$$\tan \alpha = \frac{x-x'}{\sqrt{y^2+z^2}}$$

$$\text{(If current is on x-axis then } \tan \alpha = \frac{x-x'}{\sqrt{y^2+z^2}} = \frac{x-x'}{\rho} \text{)}$$

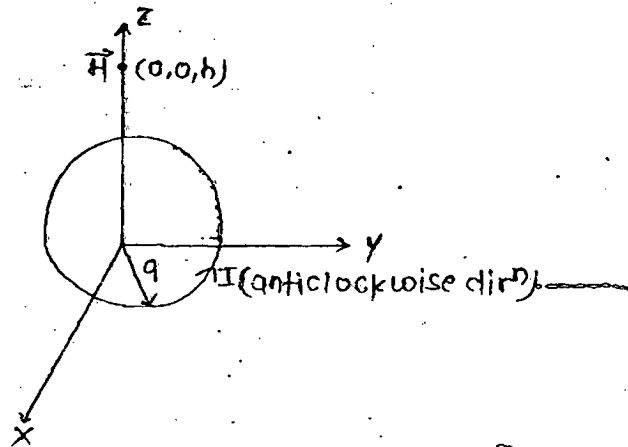
* $\alpha_1 \rightarrow$ angle of point A $(0,0,z_A)$ $P(\rho,\phi,z)$

$$\tan \alpha_1 = \frac{z - z_A}{\rho}$$

* $\alpha_2 \rightarrow$ angle of point B $(0,0,z_B)$ $P(\rho,\phi,z)$

$$\tan \alpha_2 = \frac{z - z_B}{\rho}$$

Que. $\rightarrow$ Find $\vec{M}$ at $(0,0,h)$ due to I (dc) current flowing in a circular loop having a radius (with center coinciding with z -axis) lying on xy plane as shown below.

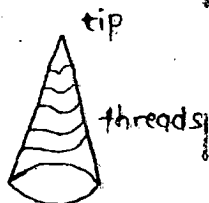


Soln.

$$\vec{M}(0,0,h) = \frac{I a^2}{2(a^2 + h^2)^{3/2}} \hat{a}_z \quad (I \text{ is in anticlockwise})$$

$$\vec{M}(0,0,h) = \frac{I a^2}{2(a^2 + h^2)^{3/2}} (-\hat{a}_z) \quad (I \text{ is in clockwise dir})$$

Note $\rightarrow$ Right hand screw law

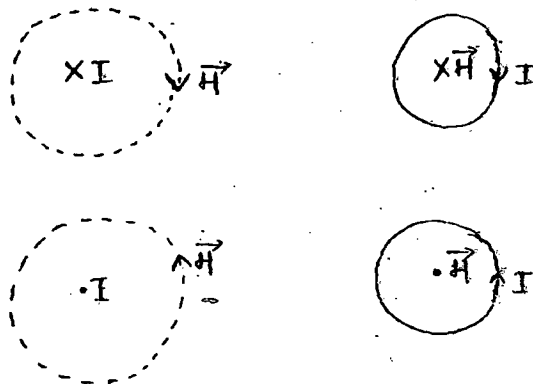


* If tip is I then take threads as $\vec{M}$

* If tip is $\vec{M}$ then take threads as I

Notation $\rightarrow$ cross(x) $\rightarrow$ in^{to} the page
 dot(.) $\rightarrow$ out of the page

eg $\rightarrow$



16/55

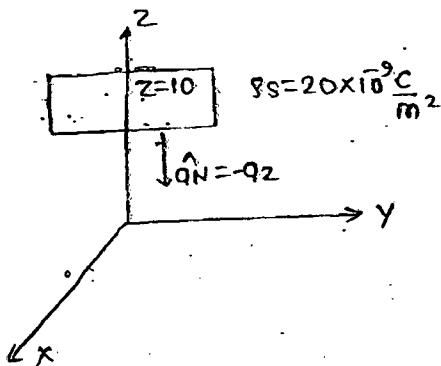
line charge $\rho_L = 30 \text{ nC/m}$ at $y=3, z=5$ (y, z are constant)
 line is parallel to x -axis

For ρ_L along x -axis $\vec{E}$ value do not depend x -axis value of field point.

$$\vec{E}|_{(0,6,1)} = 64.7 \hat{a}_y - 86.3 \hat{a}_z$$

$$\vec{E}|_{(5,6,1)} = \text{same}$$

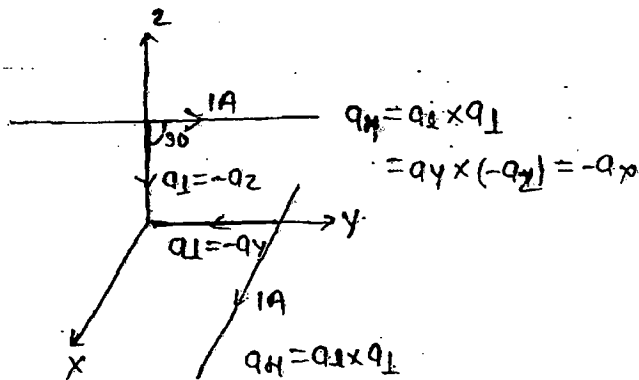
19/55



$$\vec{E} = \frac{\rho_s}{2\epsilon_0} \hat{a}_n = \frac{20 \times 10^{-9}}{2 \times \frac{1}{36\pi} \times 10^9} (-\hat{a}_z)$$

$$\vec{E} = -360\pi \hat{a}_z$$

17/55



$$q_H = q_1 \times q_2 = q_y \times (-q_x) = -q_x$$

$$q_H = q_3 \times q_4 = q_x \times (-q_y) = -q_y$$

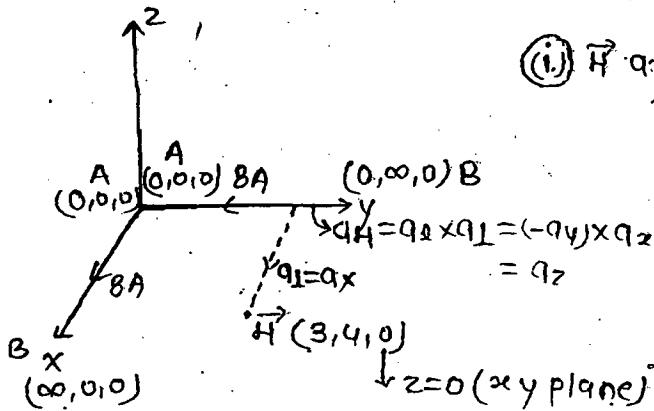
(x, z) components

13/55

* BA current is on the x-axis, the y-axis

* the dirⁿ of current is from y to x. Field at H (3,4,0)

$\vec{H}$ is linear $\vec{H}(3,4,0) = \vec{H}$ at (3,4,0) due to x line + $\vec{H}$ at (3,4,0) due to y line



(i) $\vec{H}$ at (3,4,0) due to y line

$$\vec{H} = \frac{I}{4\pi R} [-(\sin\alpha_2 - \sin\alpha_1)] q_2$$

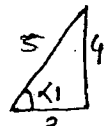
For I on y axis

$$\tan\alpha = \frac{y-y'}{x-x'} = \frac{y-y'}{\sqrt{x^2+z^2}}$$

$\alpha_1 \Rightarrow$ angle of point A (0,0,0) (x',y',z')

P(3,4,0)
x,y,z

$$\tan\alpha_1 = \frac{4-0}{\sqrt{3^2+0}} = \frac{4}{3}$$



$\alpha_2 \Rightarrow$ angle of point B (0, infinity, 0) (x',y',z')

P(3,4,0)

$$\tan\alpha_2 = \frac{4-\infty}{\sqrt{3^2+0^2}} = -\infty, \alpha_2 = -\frac{\pi}{2}$$

$$\vec{H} = \frac{I}{4\pi R} [-(\sin\alpha_2 - \sin\alpha_1)] q_2$$

$$= \frac{8}{4\pi(3)} [-(-1 - \frac{4}{5}) q_2] = \frac{8}{4\pi(3)} [\frac{9}{5} q_2] = \frac{6}{5\pi} q_2$$

Similarly $\vec{H}$ at (3,4,0) due to x line = $\frac{4}{5\pi} q_2$

$$\vec{H} = \frac{6}{5\pi} q_2 + \frac{4}{5\pi} q_2 = \frac{10}{5\pi} q_2 = \frac{2}{\pi} q_2$$

standard question

(14/55)

Ans(a)

(15/55)

I in clockwise dirⁿ $\vec{H}(0,0,h) = \frac{Ia^2}{2(a^2+b^2)^{3/2}} (-qz)$

given that $\vec{H}$ is required at the center $h=0$

$$\text{radius} = \frac{\text{diameter}}{2}$$

$$\vec{H}(0,0,0) = \frac{Ia^2}{2(a^2)^{3/2}} (-qz) = \frac{I}{2a} (-qz)$$

$$= \frac{I}{2(\frac{a}{2})} (-qz)$$

$$\vec{H} = \left(\frac{I}{a}\right) (-qz)$$

(18/55)

Ans.(c)

Note → $\vec{H}$ in all the regions due to surface (or) sheet current density

$\vec{K} \left(\frac{\text{amp}}{\text{m}} \right)$ is

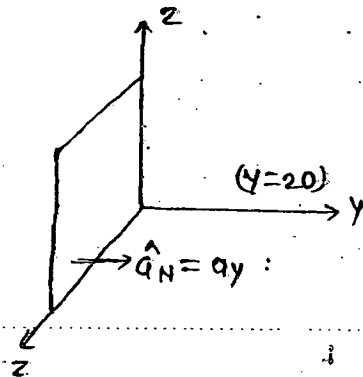
$$\boxed{\vec{H} = \frac{1}{2} \vec{K} \times \hat{a}_N}$$

Unknown $\hat{a}_N$

$$\left(\frac{\text{amp}}{\text{m}} \right) = \left(\frac{\text{amp}}{\text{m}} \right)$$

(22/56)

Given $\vec{K} = 30a_z \frac{\text{mA}}{\text{m}}$ on $y=0$ plane. Find $\vec{H}(1,20,-2)$



$$\vec{H} = \frac{1}{2} \vec{K} \times \hat{a}_N$$

$$= \frac{1}{2} (30a_z \times 10^{-3}) \times a_y$$

$$= 15 \times 10^{-3} (-a_x)$$

$$= -15a_x \left(\frac{\text{mA}}{\text{m}} \right)$$

$$= -15 \hat{i} \frac{\text{mA}}{\text{m}}$$

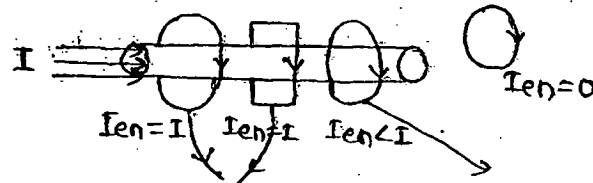
Ampere's circuital law → This law says that the closed line integral of $\vec{H}$ is equal to the current enclosed by that closed line.

mathematically

$$\oint \vec{H} \cdot d\vec{l} = I_{\text{enclosed}}$$

Unknown I_{enclosed}

example →



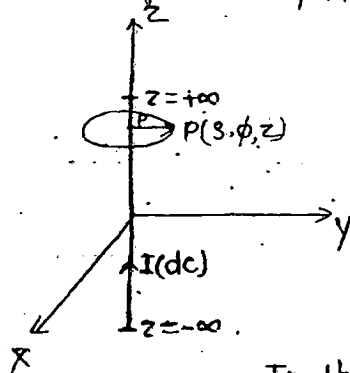
loops are encircling (or)

Total cond^r is not inside the loop.

Total cond^r is inside loops

Que → Find $\vec{H}$ in all the regions due to I (dc) flowing along z -axis.

Soln →



$$\oint \vec{H} \cdot d\vec{l} = I_{\text{enclosed}} \quad \text{--- (i)}$$

$$H \oint dl = I$$

($2\pi r$ = circumference)

In cylindrical system

$$\oint \vec{H} \cdot d\vec{l} = 4\pi r H \quad \text{--- (ii)}$$

In this case $I_{\text{enclosed}} = I$ --- (3)

From (2) (3) in eqn (i)

$$4\pi r H = I$$

$$H = \frac{I}{4\pi r} \quad \text{--- (4)}$$

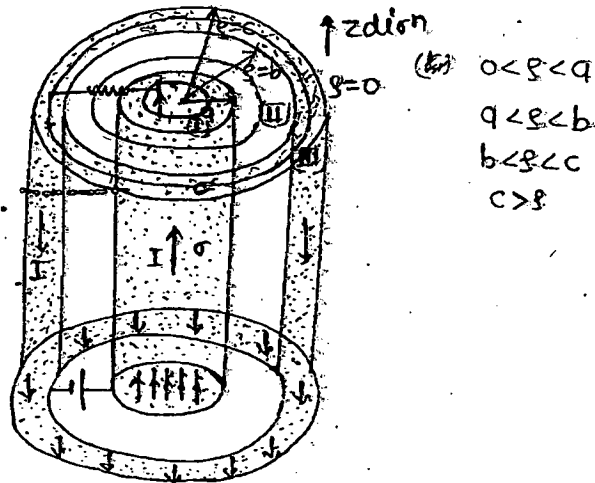
$$\vec{H} = H \hat{\phi}$$

$$\vec{H} = \frac{I}{4\pi r} \hat{\phi}$$

(IES Conventional)

Que. → Find $\vec{H}$ in all the regions due to I (dc) in inner cond^r, $-I$ (dc) in outer cond^r as shown :-

Solⁿ →



* (1) $\vec{H}$ in the region $(0 < s < a)$

$$\oint \vec{H} \cdot d\vec{l} = I_{\text{enclosed}} \quad \text{--- (i)}$$

In cylindrical $\oint H \cdot dl = H\phi(2\pi s) \quad \text{--- (ii)}$

$$\pi a^2 (\text{m}^2) \xrightarrow{\text{Current}} I$$

$$I \xrightarrow{\text{Current}} \frac{I}{\pi a^2} \left(\frac{A}{\text{m}^2} \right)$$

$$\pi s^2 \xrightarrow{\text{Current}} \frac{I}{\pi a^2} \times (\pi s^2) = I \cdot \frac{s^2}{a^2} = I_{\text{enclosed}} \quad \text{--- (iii)}$$

From (2), (3) in (1)

$$H\phi(2\pi s) = I \cdot \frac{s^2}{a^2}$$

$$H\phi = \frac{I \cdot s}{2\pi a^2} \quad \text{--- (4)}$$

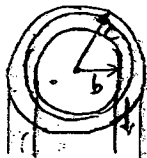
* (2) $\vec{H}$ in the region $(a < s < b)$

$$\oint \vec{H} \cdot d\vec{l} = I_{\text{enclosed}} \quad \text{--- (5)}$$

$$H\phi(2\pi s) = I$$

$$H\phi = \frac{I}{2\pi s} \quad \text{--- (6)}$$

* (3) $\vec{H}$ in the region $(b < s < c)$



$$\pi c^2 - \pi b^2 \xrightarrow{\text{Current}} -I$$

$$I \xrightarrow{\text{Current}} \frac{-I}{\pi c^2 - \pi b^2}$$

$$\pi s^2 - \pi b^2 \xrightarrow{\text{Current}} \frac{-I}{(\pi c^2 - \pi b^2)} \times (\pi s^2 - \pi b^2) = \frac{-I}{1} \left(\frac{s^2 - b^2}{c^2 - b^2} \right)$$

$$I_{\text{enclosed}} = I_{\text{inner}} + I_{\text{outer}} (\text{Inside green line})$$

$$= I - I \left(\frac{s^2 - b^2}{c^2 - b^2} \right)$$

$$I_{\text{enclosed}} = I \left(\frac{c^2 - s^2}{c^2 - b^2} \right)$$

$$\oint \mathbf{H} \cdot d\mathbf{l} = I_{\text{enclosed}}$$

$$H\phi(2\pi s) = I \left(\frac{c^2 - s^2}{c^2 - b^2} \right)$$

$$H\phi = \frac{I}{2\pi s} \times \frac{(c^2 - s^2)}{(c^2 - b^2)}$$

1* (9) $\vec{H}$ in the region $s > c$

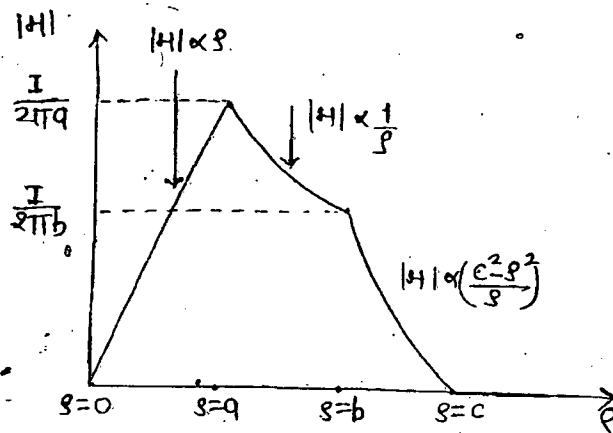
$$\oint \mathbf{H} \cdot d\mathbf{l} = I_{\text{enclosed}}$$

$$H\phi(2\pi s) = I + (-I)$$

$$H\phi(2\pi s) = 0$$

Total value of the magnetic field

$$\vec{H} = \begin{cases} \frac{I}{2\pi} \cdot \frac{s}{a^2} \phi & ; 0 < s < a \\ \frac{I}{2\pi s} \cdot \phi & ; a < s < b \\ \frac{I}{2\pi s} \left(\frac{c^2 - s^2}{c^2 - b^2} \right) \phi & ; b < s < c \\ 0 & ; s > c \end{cases}$$



Note → (1) magnetic flux density ($\vec{B} = \frac{\phi}{\text{area}}$) is given by

$$\boxed{\vec{B} = \mu \vec{H}} \left(\frac{\text{wb}}{\text{m}^2} \right) \text{ (or) Tesla} \quad \text{--- (1)}$$

$$\mu = \mu_0 \cdot \mu_r$$

μ = permeability of the medium $\left(\frac{\text{H}}{\text{m}} \right)$

$\mu_0 = 4\pi \times 10^{-7} \left(\frac{\text{H}}{\text{m}} \right)$ = permeability of free space.

$\mu_r = \frac{\mu}{\mu_0}$ = relative permeability (unitless)



I_b = Bound current { Current bounded by the nucleus }

R → Bad cond^r
C → Good dielect^r
L → magnetic material

(2) If $\vec{B}$ is given then magnetic flux (ϕ) is given by:-

$$\boxed{\phi = \iint \vec{B} \cdot d\vec{s}} \quad \text{--- (2)}$$

$$\text{wb} = \frac{\text{wb}}{\text{m}^2} \cdot \text{m}^2$$

(3) :

$$\boxed{L = \frac{N\phi}{I} \text{ (Henry)}} \quad \text{--- (3)}$$

ϕ = magnetic flux linking each turn (wb)

N = No. of turns in the coil

$N\phi$ = Total magnetic flux

I = Current in the coil

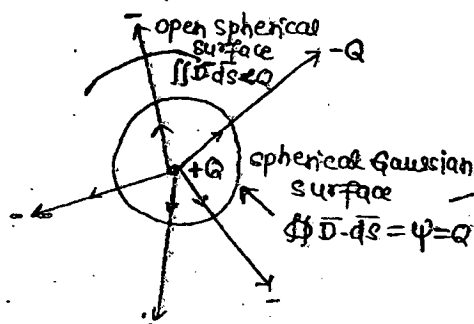
↓

L = Inductance

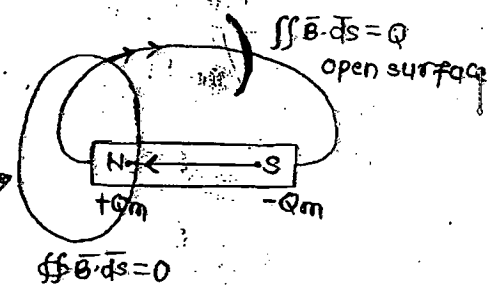
for single turn (or) single loop $N=1$

Note →

Electric field



Magnetic field



Maxwell's Equation $\rightarrow$

(1) Ampere's circuital law

$$\oint \vec{M} \cdot d\vec{l} = I \quad \text{--- (i)}$$

By definition $I = \iint \vec{J} \cdot d\vec{s} \quad \text{--- (ii)}$

By Stokes theorem $\oint \vec{M} \cdot d\vec{l} = \iint (\vec{\nabla} \times \vec{M}) \cdot d\vec{s} \quad \text{--- (3)}$

From (2), (3) in (1)

$$\iint (\vec{\nabla} \times \vec{M}) \cdot d\vec{s} = \iint \vec{J} \cdot d\vec{s}$$

Compare $\boxed{\vec{\nabla} \times \vec{M} = \vec{J}}$

(2) Gauss law of magnetic field

$$\oint \vec{B} \cdot d\vec{s} = 0 \quad \text{--- (1)}$$

Using divergence theorem

$$\oint \vec{B} \cdot d\vec{s} = \iiint (\vec{\nabla} \cdot \vec{B}) \, dv \quad \text{--- (2)}$$

From (2) in (1) $\iiint (\vec{\nabla} \cdot \vec{B}) \, dv = 0$

$$\iiint (\vec{\nabla} \cdot \vec{B}) \, dv = \iiint 0 \, dv$$

Compare $\vec{\nabla} \cdot \vec{B} = 0$

Note $\rightarrow$ Maxwell's eqn for static fields.

(1) $\vec{\nabla} \cdot \vec{D} = \rho_v$

(2) $\vec{\nabla} \times \vec{E} = 0$ (Static elec. field is irrotational)

(3) $\vec{\nabla} \times \vec{M} = \vec{J}$ (Static mag. field is rotational)

(4) $\vec{\nabla} \cdot \vec{B} = 0$ (Static mag. field is divergence free)

(Derivation not Req.)

Que $\rightarrow$ Find inductance between $r=a$ & $r=b$ of a coaxial cable for 'h' height.

Ans $\rightarrow$

$$L = \frac{\mu h}{2\pi} \ln\left(\frac{b}{a}\right)$$

$$\vec{M} = \frac{I}{2\pi r} \hat{\phi}, \quad a < r < b$$

$$\vec{B} = \mu \vec{M} = \frac{\mu I}{2\pi r} \hat{\phi}$$

$$\phi = \iint \vec{B} \cdot d\vec{s} = - \iint \left(\frac{\mu I}{2\pi r} a \phi \right) (dr dz a \phi) \quad \text{---}$$

$$= \frac{\mu I}{2\pi} \int_{r=a}^b \frac{dr}{r} \cdot \int_{z=0}^h dz$$

$$= \frac{\mu I}{2\pi} (\ln r)_a^b (z)_0^h$$

$$\phi = \frac{\mu I}{2\pi} \ln\left(\frac{b}{a}\right) h$$

$$\boxed{L = \frac{\phi}{I} = \frac{\mu h}{2\pi} \ln\left(\frac{b}{a}\right) \text{ Henry}}$$

* Inductance per meter length of a coaxial cable is -

$$\boxed{\frac{L}{h} = \frac{\mu}{2\pi} \ln\left(\frac{b}{a}\right) \left(\frac{H}{m}\right)}$$

(2) Inductance of N turn coil (Solenoidal)

$$\vec{H} = \frac{NI}{d} a_z \left(\frac{amp}{m} \right)$$

$$\vec{B} = \mu \vec{H}$$

$$\vec{B} = \frac{\mu NI}{d} a_z$$

$$\phi = \iint \vec{B} \cdot d\vec{s} = \iint \left(\frac{\mu NI}{d} \right) a_z [r dr d\phi a_z]$$

$$= \frac{\mu NI}{d} \int_{r=0}^a r dr \int_{\phi=0}^{2\pi} d\phi$$

$$= \frac{\mu NI}{d} \left(\frac{r^2}{2} \right)_0^a (\phi)_0^{2\pi}$$

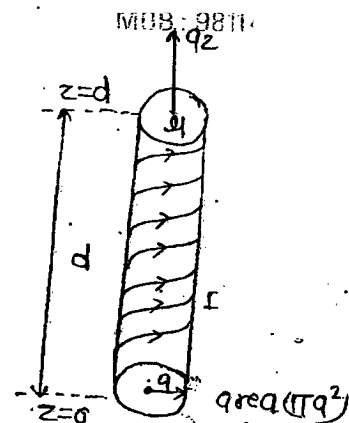
$$\phi = \frac{\mu NI}{d} (\pi a^2)$$

$$L = \frac{N\phi}{I}$$

$$L = N \cdot \frac{\mu NI}{d} (\pi a^2)$$

$$\boxed{L = \frac{\mu N^2}{d} (\pi a^2)}$$

$$L = \frac{\mu N^2}{d} \left[\text{Cross sectional area} \right]$$



Note →

* (1) $NT \Rightarrow \phi = LI$; $w_{ind} = \frac{1}{2} LI^2 = \frac{1}{2} \phi I = \frac{1}{2} \frac{\phi^2}{L}$ (Joule)

$EMT \Rightarrow B = \mu H$; $w_{mag. field} = \frac{1}{2} \mu H^2$

(Energy stored in magnetic field) $= \iiint \frac{1}{2} \mu H^2 dV = \iiint \frac{1}{2} \vec{B} \cdot \vec{H} dV = \iiint \frac{1}{2\mu} B^2 dV$ (Joule)

* (2) Magnetic energy density $= \frac{1}{2} \mu H^2$

$$= \frac{1}{2} \vec{B} \cdot \vec{H}$$

$$= \frac{1}{2} \frac{B^2}{\mu} \left(\frac{\text{Joule}}{\text{m}^3} \right)$$

* (3) $\vec{J} \cdot \vec{E} = \sigma \vec{E} \cdot \vec{E} = \sigma |\vec{E}|^2 \left(\frac{\text{Watts}}{\text{m}^3} \right)$

$$\left(\frac{A}{m^2} \right) \left(\frac{V}{m} \right) = \left(\frac{W}{m^3} \right)$$

$$R = \frac{1}{\sigma A}$$

= Power dissipation density of a material

(1) Scalar Electric Potential →

$$\vec{E} = -\vec{\nabla} V$$

(Volt/m) ↓ scalar electric potential

(2) Scalar Magnetic Potential →

$$\vec{H} = -\vec{\nabla} V_m$$

$\left(\frac{\text{Amp}}{m} \right) \left(\frac{1}{m} \right) \rightarrow \frac{\text{Amp}}{m^2}$

provided $\vec{J} = 0$

where V_m = scalar magnetic potential

From Maxwell eqⁿ: $\nabla \times \vec{H} = \vec{J}$

$$-\nabla \times (\nabla V_m) = \vec{J}$$

curl of grad = 0

$$0 = \vec{J}$$

The above concept is applicable for $\vec{J} = 0$

(3) Vector Magnetic Potential $\rightarrow$

We know that $\nabla \cdot \vec{B} = 0$ — (1) {Emf}

& also $\nabla \times (\nabla \times \vec{A}) = 0$ — (2) {mathes}

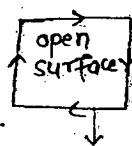
From eqn (1) & (2)

$$\nabla \cdot \vec{B} = \nabla \cdot (\nabla \times \vec{A})$$

$$\boxed{\begin{matrix} \vec{B} = \nabla \times \vec{A} \\ \left(\frac{\text{wb}}{\text{m}^2}\right) \quad \left(\frac{1}{\text{m}}\right) \left(\frac{\text{wb}}{\text{m}}\right) \\ \quad \quad \quad ? \end{matrix}} \quad \left\{ \vec{A} = \frac{1}{4} (\nabla \times \vec{A}) \right\}$$

Where; $\vec{A}$ = Vector magnetic potential $\left(\frac{\text{wb}}{\text{m}}\right)$

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$$\oint \vec{A} \cdot d\vec{l} = \phi$$

$$\left(\frac{\text{wb}}{\text{m}}\right) \cdot \text{m} = \text{wb}$$

$$\oint \vec{A} \cdot d\vec{l} = \iint (\nabla \times \vec{A} \cdot d\vec{s})$$

$$\text{wb} = \text{wb}$$

Ans. (a)

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$$\frac{1}{2} \vec{J} \cdot \vec{A} = \frac{\text{magnetic energy}}{\text{m}^3} \quad \omega_L = \frac{1}{2} LI^2 = \frac{1}{2} \phi I$$

$$\left(\frac{\text{A}}{\text{m}}\right) \left(\frac{\text{wb}}{\text{m}}\right)$$

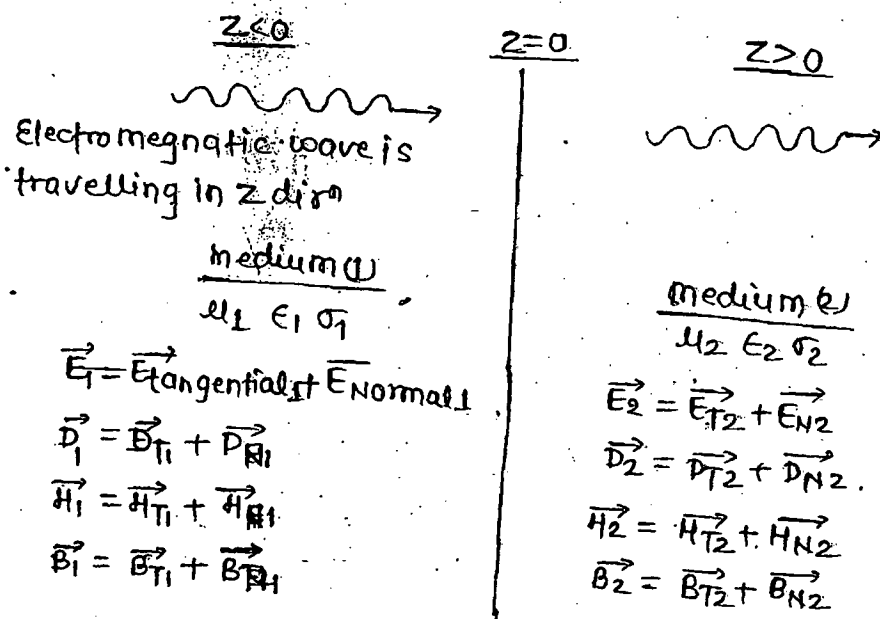
$(\text{wb})(\text{Amp}) = \text{magnetic energy}$

= magnetic energy density

Ans (b)

* Boundary Conditions $\rightarrow$

- * Boundary is a surface (whose thickness $\rightarrow 0$) which connects medium 1, medium 2.
- * Boundary condition give the relation between fields in one medium, fields in other medium.
- * If fields in one medium are known, then using boundary condn we can find fields in other medium.



tangential intensities ($\vec{E}, \vec{H}$)

Normal densities ($\vec{p}, \vec{B}$)

$Q, \rho_s, \rho_s, \rho_v$
C/m²

$I, \vec{K}, \vec{J}$
A/m

$\epsilon/m^2 \vec{D}_{N1}$

A/m $\vec{H}_{T1}$

$\vec{B}_{N1}$

$\vec{E}_{T2}$
 $\vec{D}_{N2} + \rho_s(C/m^2)$
 $\vec{H}_{T2} + \vec{K}(A/m)$
 $\vec{B}_{N2}$

$\vec{E}_{T1} = \vec{E}_{T2}$

$\vec{D}_{N1} - \vec{D}_{N2} = \rho_s$ (scalar) (C/m²)

$\vec{H}_{T1} - \vec{H}_{T2} = \vec{K} \times \vec{r}$ (vector) (A/m)

$\vec{B}_{N1} = \vec{B}_{N2}$

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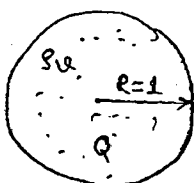
$\vec{H} = \frac{I}{2\pi} \frac{\rho}{q^2} q \phi, \quad 0 < \rho < q$

given $\rho = r, q = R$ ($r < R$)

$\vec{H} = \frac{I}{2\pi} \frac{\pi}{R^2} q \phi$

$|\vec{H}| = \frac{I}{2\pi} \frac{\pi}{R^2}$

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within a unit sphere ($R=1$ meter $\rightarrow$ volume charge configuration)

$Q = \iiint \rho_v dV$

$V = -\frac{6\pi^5}{\epsilon_0}$ For (If in question not given then take homogeneous)

From Poisson's eqⁿ

$$\nabla^2 V = \frac{-\rho_v}{\epsilon_0}$$

$$\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial V}{\partial r} \right) = \frac{-\rho_v}{\epsilon_0}$$

$$\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \left\{ \frac{-6r^5}{\epsilon_0} \right\} \right) = \frac{-\rho_v}{\epsilon_0}$$

$$\frac{1}{r^2} \frac{\partial}{\partial r} \left[r^2 \times \frac{-5r^4 \times 6}{\epsilon_0} \right] = \frac{-\rho_v}{\epsilon_0}$$

$$\frac{1}{r^2} (-30) 6 \frac{r^5}{\epsilon_0} = \frac{-\rho_v}{\epsilon_0}$$

$$\frac{r^3}{\epsilon_0} \times 180 = \frac{\rho_v}{\epsilon_0}$$

$$\rho_v = 180 r^3$$

$$Q = \iiint \rho_v d\tau$$

$$= \iiint 180 r^3 (r^2 \sin \theta dr d\theta d\phi)$$

$$= 180 \int_{r=0}^1 r^5 dr \int_{\theta=0}^{\pi} \sin \theta d\theta \int_{\phi=0}^{2\pi} d\phi$$

$$Q = 120C$$

23/56 One direction $\rightarrow$ Let x dirⁿ

given that Laplace eqn is satisfied.

$$\nabla^2 V = 0 \quad \text{--- (i)}$$

$$\frac{\partial^2 V}{\partial x^2} = 0$$

$$\int \frac{\partial^2 V}{\partial x^2} dx = \int 0 dx$$

$$\frac{\partial V}{\partial x} = 0 + A$$

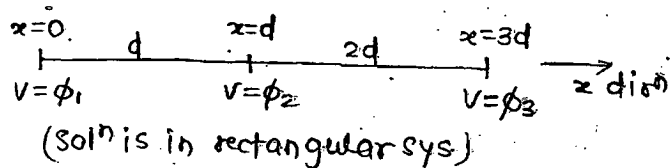
$$\partial V = A dx$$

$$V = Ax + B \quad \text{--- (ii)}$$

$$\text{Given } V = \phi_1 \text{ at } x = 0 \quad \text{--- (3)}$$

$$\text{From (3) in (ii) } \phi_1 = A(0) + B, \quad B = \phi_1 \quad \text{--- (4)}$$

$$V = Ax + \phi_1$$



$$V = \phi_2 \text{ at } x = d$$

$$\phi_2 = A(d) + \phi_1 \Rightarrow A = \frac{\phi_2 - \phi_1}{d}$$

$$V = \left(\frac{\phi_2 - \phi_1}{d} \right) x + \phi_1$$

$$V = \phi_3 \text{ at } x = 3d$$

$$\phi_3 = \frac{\phi_2 - \phi_1}{d} (3d) + \phi_1$$

$$\phi_3 = 3\phi_2 - 3\phi_1 + \phi_1$$

$$\phi_3 + 2\phi_1 = 3\phi_2$$

$$\phi_2 = \frac{\phi_3 + 2\phi_1}{3}$$

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$$\epsilon_r = 5, \bar{D} = 20 \text{ C/m}^2$$

$$\bar{P} = \left(1 - \frac{1}{\epsilon_r} \right) \bar{D}$$

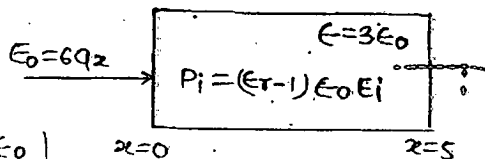
$$\bar{P} = 1.6 \text{ C/m}^2$$

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$$\bar{P}_i = (\epsilon_r - 1) \epsilon_0 E_i$$

$$= (3 - 1) \epsilon_0 \cdot \frac{6Qx}{3} \quad \left(\because E_i \propto \frac{\epsilon_0}{\epsilon_r} \right)$$

$$\bar{P}_i = .4 \epsilon_0 Qx$$



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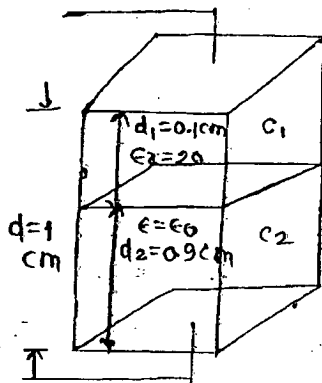
$$\omega = \frac{1}{2} QV, \quad V = \frac{Q}{4\pi\epsilon r}$$

$$\omega \propto V \propto \frac{1}{r}$$

$$\frac{\omega_2}{\omega_1} = \frac{r_1}{r_2}$$

$$\frac{\omega_2}{\omega_1} = \frac{0.5}{1}, \quad 2\omega_2 = \omega_1$$

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$$C_1 = \frac{\epsilon_1 A}{d_1}, \quad C_2 = \frac{\epsilon_2 A}{d_2}$$

$$C = \frac{1}{\frac{1}{C_1} + \frac{1}{C_2}} = \frac{1}{\frac{d_1}{\epsilon_1 A} + \frac{d_2}{\epsilon_2 A}}$$

$$D = \frac{Q}{A} = \frac{Q}{A} = \frac{CV}{A}$$

$$E_1 = \frac{D}{\epsilon_1}$$

$$E_2 = \frac{D}{\epsilon_2}$$

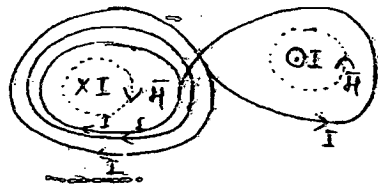
$$D \neq \frac{C \times 100}{\epsilon_1}$$

$$D \neq 1$$

$$\frac{V_1}{d_1} = \frac{D}{\epsilon_1} \quad \frac{V_2}{d_2} = \frac{D}{\epsilon_2}$$

(41)
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$$\oint \mathbf{H} \cdot d\mathbf{l} = I_{\text{enclosed}}$$



$$3I + I = 4I$$

* Remaining part of the boundary condⁿ:-

* There are 4 boundary conditions:-

(1) The tangential components of electric field intensities are continuous at the boundary surface.

$$\text{mathematically } E_{\tan 1} = E_{\tan 2} \quad (\text{or}) \quad \begin{matrix} \vec{E}_{\tan 1} & = & \vec{E}_{\tan 2} \\ (\text{mag.}) & & (\text{vec}) \end{matrix}$$

(2) The normal components of electric flux densities are discontinuous (not equal) by an amount equal to the surface charge density on the boundary surface

$$\boxed{D_{N1} - D_{N2} = \rho_s} \quad \text{if } \rho_s = 0 \text{ then } D_{N1} = D_{N2} \{ \vec{D}_{N1} = \vec{D}_{N2} \}$$

(3) The tangential components of magnetic field intensities are discontinuous at the boundary by an amount equal to surface current density ($\vec{K}$) on the boundary surface

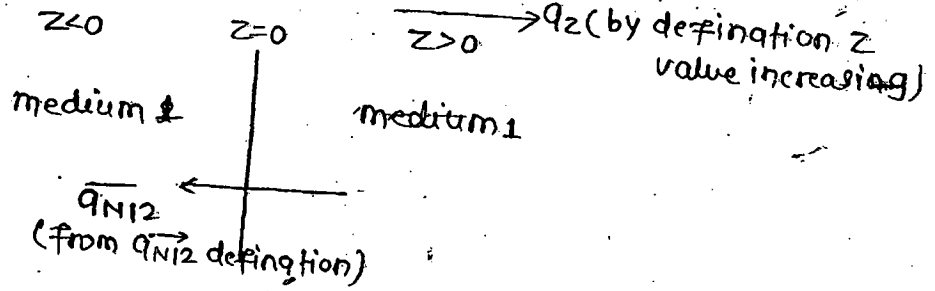
$$\boxed{\vec{H}_{t1} - \vec{H}_{t2} = \vec{K}_{N12} \times \vec{K}} \quad \text{if } \vec{K} = 0 \text{ then } \vec{H}_{t1} = \vec{H}_{t2}$$

(4) The normal components of magnetic flux densities are continuous (equal) at the boundary surface

$$\boxed{B_{N1} = B_{N2}} \quad \vec{B}_{N1} = \vec{B}_{N2}$$

$\vec{K}_{N12}$ = normal unit vector from medium 1 to medium 2

Example →



Compare $\vec{q}_{N12}$, $\vec{q}_z$ both are in opposite direction $\vec{q}_{N12} = -\vec{q}_z$

Note → For $z=0$ {or $z=\text{constant}$ } boundary surface
 $\vec{z}$ compared of the vector is normal (90°) other two are tangential
 (parallel to the surface)

Types of boundaries →

(1) Dielectric & dielectric boundary →

medium (1)	medium (2)
$\sigma_1 \approx 0$, $\mu_1 = \mu_0 \mu_{r1}$	$\sigma_2 \approx 0$, $\mu_2 = \mu_0 \mu_{r2}$
$\epsilon_1 = \epsilon_0 \epsilon_{r1}$	$\epsilon_2 = \epsilon_0 \epsilon_{r2}$

In this case boundary conditions are same as above 4 condⁿ

(2) Dielectric & cond^r boundary →

medium (1)	medium (2)
$\sigma_1 \approx 0$, μ_1, ϵ_1	$\sigma_2 \approx \infty$, μ_2, ϵ_2
	$\vec{E}_2 = \frac{\vec{J}_2}{\sigma_2(\rightarrow \infty)} = 0$
	$E_2 = 0$
	$\vec{E}_{t2} + \vec{E}_{N2} = 0$
	$E_{t2} = 0$ — (i)
	$E_{N2} = 0$ — (ii)

(i) In general boundary condⁿ $E_{t1} = E_{t2}$ — (iii)

From (i) in (iii) $E_{t1} = 0$ (or) $\vec{E}_{t1} = 0$

On the cond^r boundary (or) surface $\vec{E}_{\text{tangential}}$ is 0.

(ii) $D_{N1} - D_{N2} = \rho_s$

$D_{N1} - \epsilon_2 E_{N2} = \rho_s$ — (iv)

From (2) in (4)

$$D_{N1} - 0 = \rho_s$$

$$\begin{aligned} D_{N1} &= \rho_s \\ \epsilon_1 E_{N1} &= \rho_s \end{aligned}$$

Normal component of electric flux density is equal to ρ_s on the cond^r surface