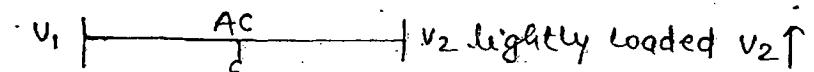


HVDC

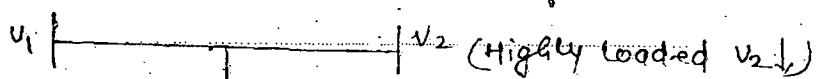
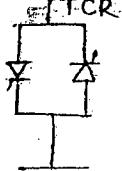
* We can transmit the power by using EHVAC (Or) HVDC.

Features of AC lines:-

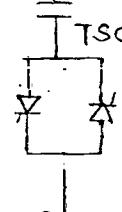
- (1) The power flow magnitude & dirn can't be quickly & easily control.
- (2) The transient stability limit is lesser in the AC line when compared with dc line.
- (3) The other prob. associated with AC lines are skin effect; corona losses; radio & TV interference b/w the comm. lines & power lines.



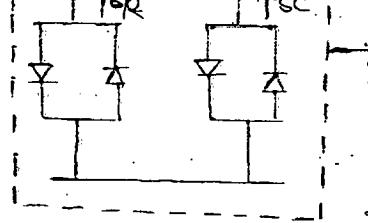
V_2 lightly loaded $V_2 \uparrow$
TCR → thyristorised control
Reactor



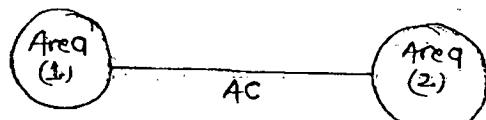
V_2 (Highly loaded $V_2 \downarrow$)
TSC → Thyristorised switch capacitor



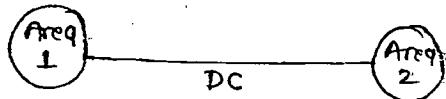
TSC
TSC → SVC (static vars compensating)



- (4) Intermediate substation are installed in the ac line to compensate the reactive power automatically as per the requirement of the line.



Synchronous tie [frequencies must be same]



Asynchronous tie [freq. need not be same].

- (5) The sys. disturbance in one of area results in power swings.
If the power swings are unstable then it may lead to cascading of tripping the alternators & this results in large scale blackouts.
- (6) With ac interconnection the freq. disturbance in one area is transferred to other area.
- (7) If multiple no. of areas is interconnected by ac line then the fault level of the system increases.

8

* HVDC → It is economical to xmit bulk power over long distance.

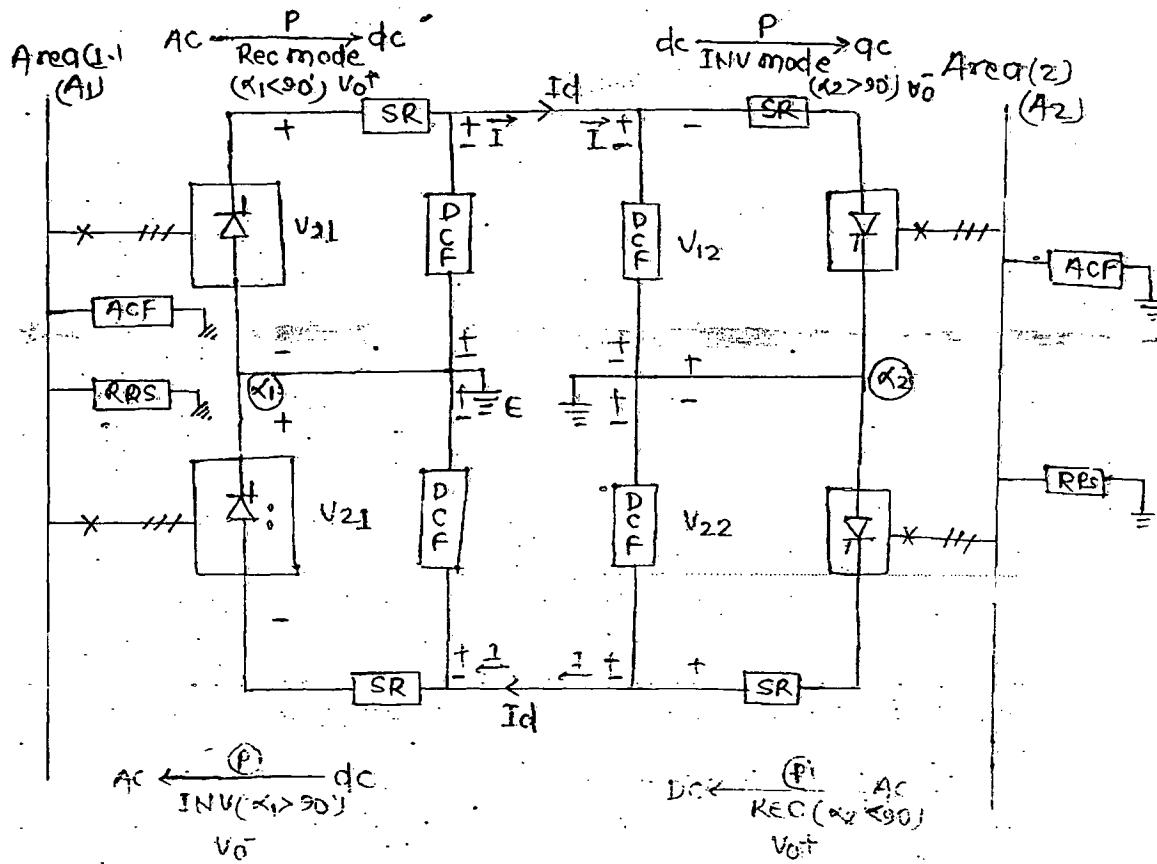
Advantages →

- (1) The power flow magnitude & dirn can be quickly & easily controlled.
- (2) The transient stability limit is improved in the dc line.
- (3) There is no skin effect prob. in the dc line.
- (4) The other prob. like corona losses, radio & tv interference is very much reduced in the dc lines.
- (5) HVDC is used for underground or submarine cables even for short distance (because dc cables will not charge continuously)
- (6) HVDC can utilise earth for its return path.
- (7) The power xⁿ capacity of a bipolar HVDC line is almost same as that of 3φ single ckt ac line.
- (8) We can interconnect 2 independant areas at different freq. because it is an asynchronous type.
- (9) With dc interconnection the freq. disturbance in one area can't be transferred to other area.

(lo) If multiple no. of areas are interconnected with dc line then the fault level of the sys. will not be substantially increased.

Type of HVDC →

(i) Bipolar HVDC →



SR → smoothing Reactor

DCF → DC Filter

ACF → AC Filter

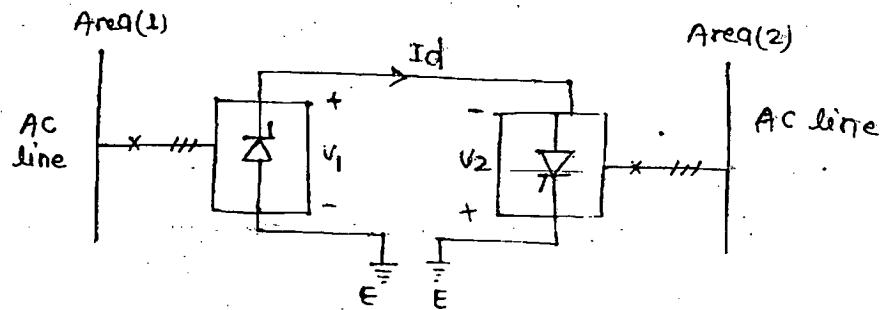
RPS → Reactive power source (To compensate the required Power for converter operation)

$\{ \pm \text{Ref} \}$

$\{ \pm \text{Actual } (A_1 \rightarrow A_2) \}$

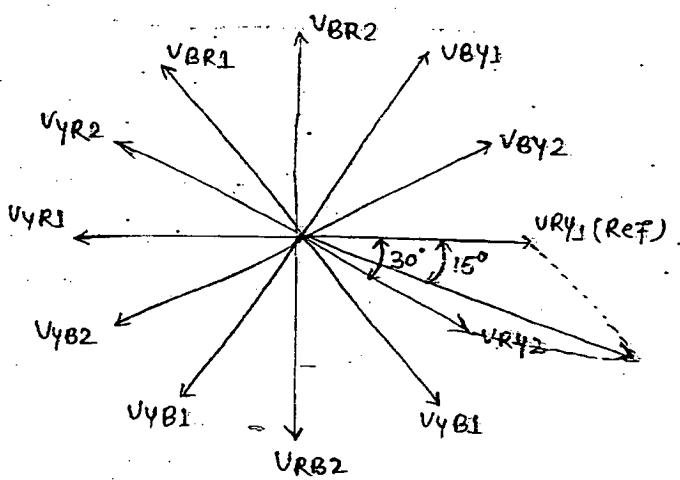
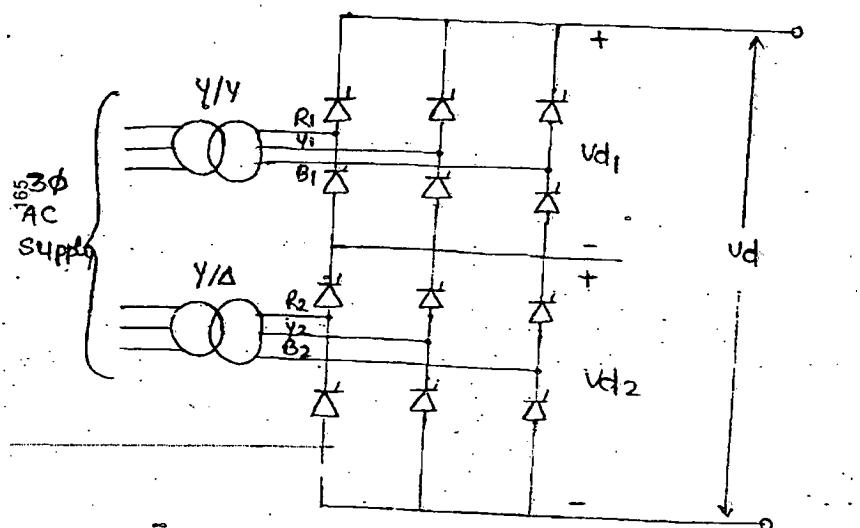
$\{ \pm \text{Actual } (A_1 \leftarrow A_2) \}$

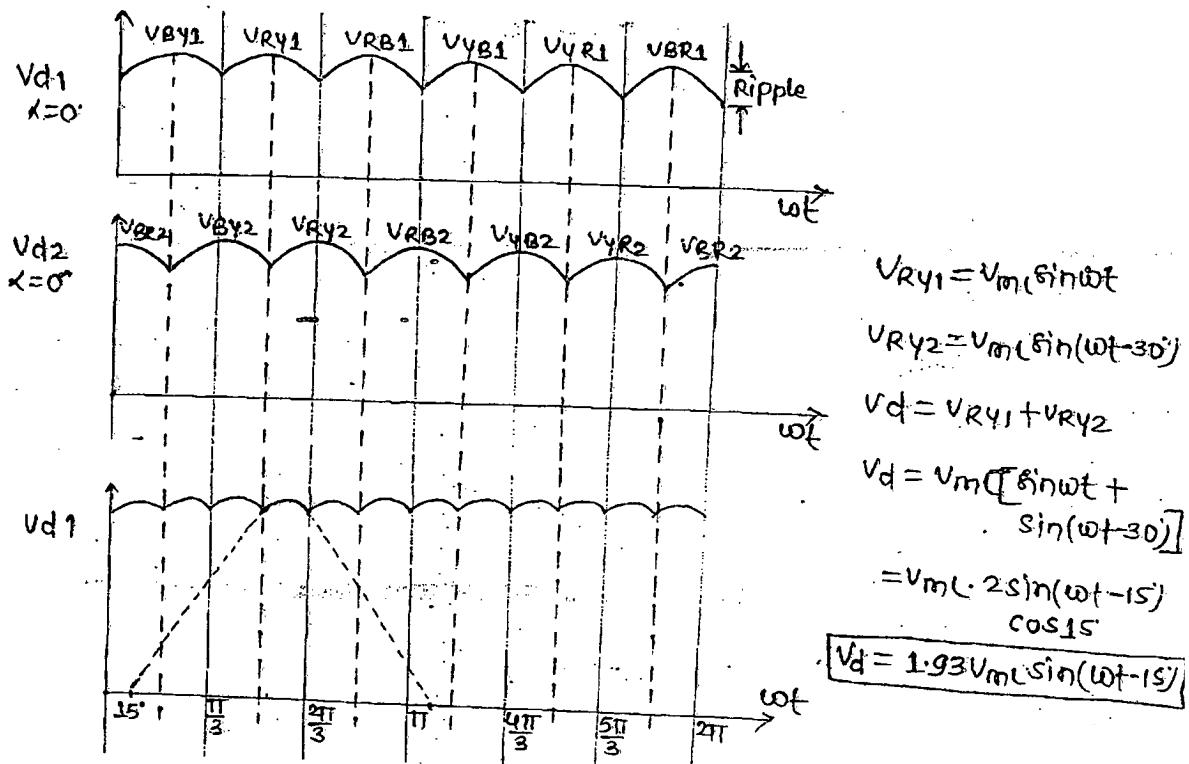
(2) Monopolar HVDC →



* In order to reduce the harmonics the 6 pulse con^r is replaced by the 12 pulse con^r.

12 pulse converter →





Harmonics On AC side →

Harmonics on AC side of m pulse convr (I_s) → ~~mRTE~~

Harmonics on AC side of 2 pulse convr (I_s) → $2k \pm 1 = 3, 5, 7, 9, \dots$

6 pulse convr (I_s) → $6k \pm 1 = 5, 7, 11, 13, \dots$

12 pulse convr (I_s) → $12k \pm 1 = 11, 13, 23, 25, \dots$

Harmonics on dc side →

Harmonics on dc side of m puls convr (V_o) = mK

2 pulse convr (V_o) = $2K$

6 pulse convr (V_o) = $6K$

12 pulse convr (V_o) = $12K$

(11)
57

$\frac{V}{F}$ control of IM

$$N_s = \frac{120F}{P} = \frac{120 \times 50}{2} = 3000 \text{ rpm}$$

$$\therefore S_r = \frac{N_s - N_r}{N_s} = \frac{3000 - 2850}{3000} = 0.05$$

NS for 40 Hz

$$N_S = \frac{120F}{P} = \frac{120 \times 40}{2} = 2400$$

$$\frac{1}{2} S_T = \frac{N_S - N_T}{N_S}$$

$$\frac{0.05}{2} = \frac{2400 - N_T}{2400}$$

$$N_T = 2340 \text{ rpm}$$

(14)
58

$$V_o = E_b + I_o R_q \rightarrow \text{Neglected}$$

$$\frac{3U_m}{\pi} \cos \alpha = 220$$

$\therefore E_b \propto N$
It half the rated speed

$$\frac{3 \times 440 / 2 \cos \alpha}{\pi} = 220$$

$$\frac{N}{2} \propto \frac{E}{2} \propto \frac{440}{2} = 220$$

$$PF = \frac{3}{\pi} \cos \alpha = \frac{1}{2\sqrt{2}}$$

$$\alpha = 0.354 : \quad \frac{3}{\pi} \cos \alpha = 0.354$$

(15.)
58

$\alpha \downarrow, V_o \uparrow, \omega \uparrow$

Regenerated Power = $V_o \cdot I_o$

$$= U_s (1 - \alpha) I_o$$

$$= 600 (1 - 0.7) 100$$

$$= 18 \text{ kW}$$

Because Regenerative
braking is done only in Boost
cont.
Hence $V_o = U$.

(16)
58

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Inverter Question

(1)
49

$$2d = 120^\circ$$

$$d = 60^\circ$$

$$V_{on} = \frac{2\sqrt{2}}{\pi} \sin d \cdot V_s$$

$$V_{o1} = \frac{2\sqrt{2}}{\pi} \sin d \cdot V_s$$

$$= \frac{2\sqrt{2}}{\pi} \cdot 1 \cdot \sin d$$

$$= 0.78V$$

(4)
49

$$\frac{V_{o2}}{(V_{o1})_{max}} = \frac{2\sqrt{2}}{3\pi} V_s \cdot \sin 3d$$

$$= \frac{2\sqrt{2}}{3} \frac{V_s}{\pi} \sin 3d = 19.6V$$

(5)
49

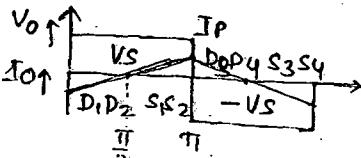
$$g = \frac{2\sqrt{2} \sin d}{\sqrt{(ed)\pi}} \quad 2d = 150^\circ = \frac{5\pi}{6} \text{ rad}$$

$$d = 75^\circ$$

$$g = \frac{2\sqrt{2} \cdot 0.95}{\sqrt{\frac{5\pi}{6}}} \quad g = 0.95$$

$$THD = 31.8\%$$

(7)
50



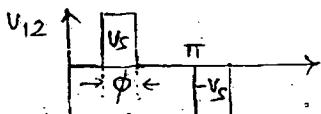
$\pi/2$ to π ; $S_1, S_2 \rightarrow ON$, $V_o = V_s$

$$\frac{di}{dt} = V_s, \quad \int di = \frac{V_s}{\omega L} \int d(\omega t)$$

$$I_p = \frac{V_s}{\omega L} \cdot \frac{\pi}{2} = \frac{V_s}{4fL} = 10A$$

(11)
50

$$V_{12} = V_1 - V_2$$



$$V_{12} = V_s \left(\frac{\phi}{\pi} \right)^{1/2}$$

(12)
50

$$|Z_n| = X_n = n\omega L$$

$$V_{on} = k_n \cdot V_{o1} \quad (k_n < 1)$$

$$I_{on} = \frac{V_{on}}{|Z_n|} = \frac{k_n V_{o1}}{n \cdot \omega L} = \frac{k_n}{n} I_{o1}$$

conv. (1) \rightarrow

$$(1) RLC; \quad \omega t_c = \phi = \tan^{-1} \frac{X_C - X_L}{R}; \quad \omega = \frac{2\pi}{T} = \frac{2\pi}{0.2 \times 10^3}$$

$$\tan(\omega t_c) = \frac{X_C - X_L}{R} \quad t_c = (SE) t_0 = 2.42 \times 10^{-6}$$

$$\tan \left[\frac{2\pi}{0.2 \times 10^3} \times \frac{24 \times 10^6}{x(180)} \right] = \frac{X_C - 12}{3} = 24 \times 10^6$$

$$X_C = 14.7 \Omega, \quad \frac{1}{\omega C} = 14.7$$

$$C = 2.15 \mu F$$

(13)
51

$$D \rightarrow \phi = \tan^{-1} \frac{X_C - X_L}{R}$$

$$= \tan^{-1} \left(\frac{X_C - 0}{0} \right) = 90^\circ$$

$$\omega t = \pi/2 \text{ rad}$$

$$t = \pi/2\omega \text{ rad} = \frac{1}{4f} \text{ sec}$$

$$t = 5 \text{ ms}$$