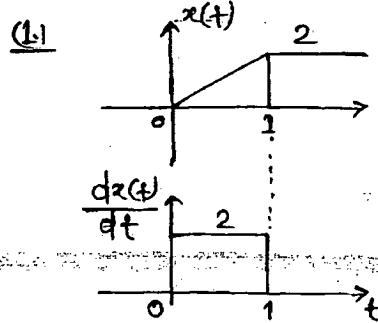


Chapter-02
 Different Operations of
 Signal

(1) Differentiation →

$$x(t) = \frac{dx(t)}{dt} = \text{slope of } x(t) \text{ w.r.t. } t$$

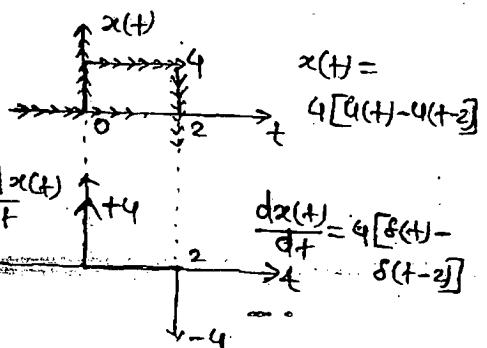
* Graphical diff is applicable for triangular & rectangular type signal.



$$x(t) = 2x(t) - 2x(t-1)$$

$$\frac{dx(t)}{dt} = 2u(t) - 2u(t-1)$$

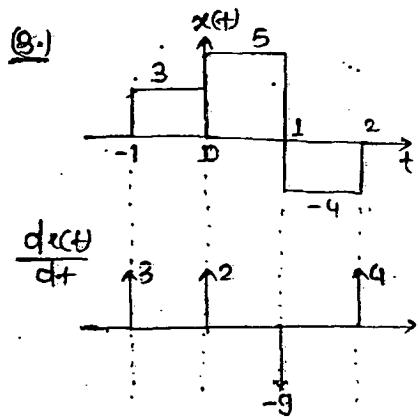
(2.)



$$x(t) =$$

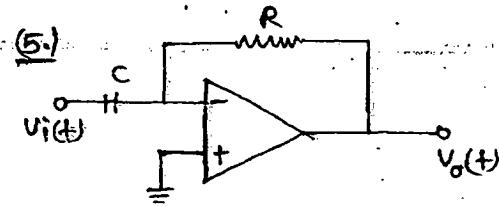
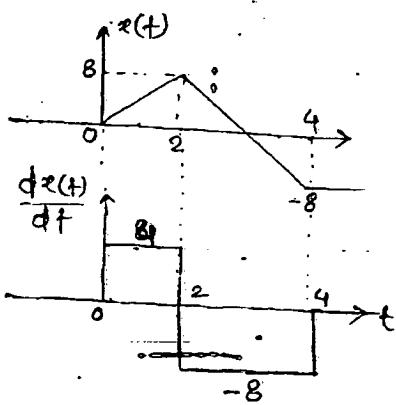
$$4[u(t) - u(t-1)]$$

$$\frac{dx(t)}{dt} = 4[\delta(t) - \delta(t-1)]$$



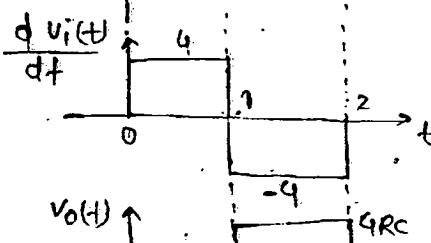
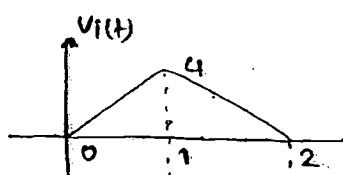
$$\frac{dx(t)}{dt}$$

(4.)



$$V_o(t) = -RC \frac{dV_i(t)}{dt}$$

amp reversal

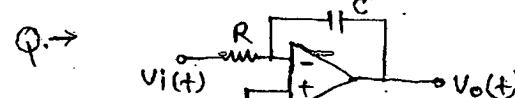
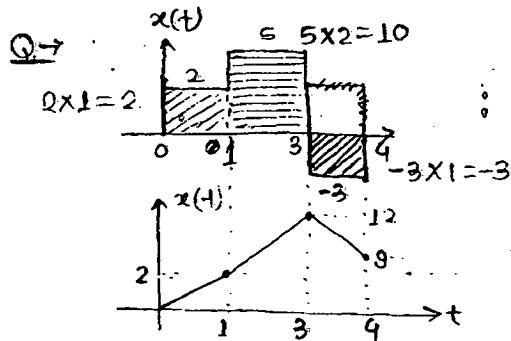
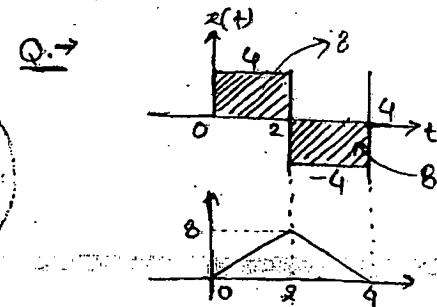
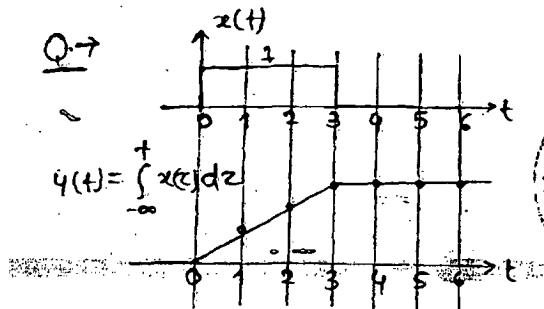


(2) Integration →

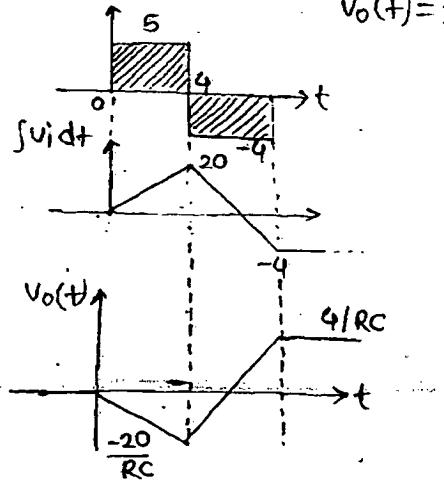
$$x(t) = y(t) = \int_{-\infty}^t x(z) dz$$

= area of signal $x(t)$ w.r.t 't'

* Graphical integration is applicable only for rectangular type waveform.



$$V_o(t) = -\frac{1}{RC} \int v_i dt$$



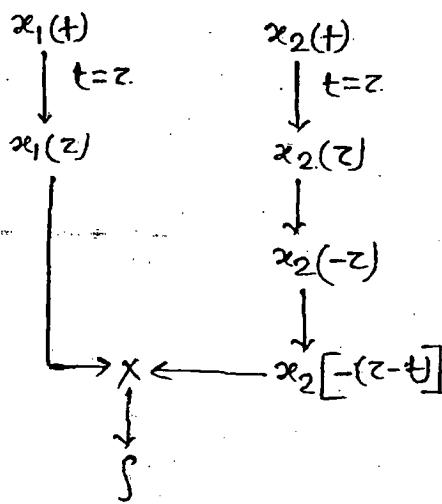
$$\text{Total area} = 2 + 10 - 3 = 9$$

(3) Convolution → It is a mathematical operator & it is used for calculation of response of LTI system.

$$y(t) = x_1(t) * x_2(t)$$

$$= \int_{-\infty}^{\infty} x_1(z) \cdot x_2(t-z) dz$$

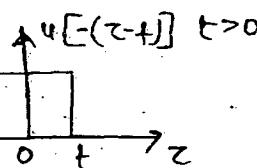
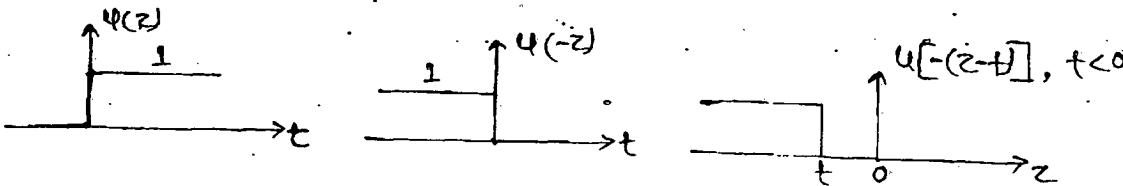
$$x_1(t) * x_2(t) = \int_{-\infty}^{\infty} x_1(z) \cdot x_2(t-z) dz$$

Steps →

- (1) Folding
- (2) shifting
- (3) multiplication
- (4) Integration.

Q.7 $y(t) = u(t) * u(t)$

Soln $= \int_{-\infty}^{\infty} u(z) \cdot u(t-z) dz$



$$y(t) = \int_{-\infty}^{\infty} u(z) \cdot u(t-z) dz$$

$$= \begin{cases} 0 & ; t < 0 \\ \int_0^t dt & ; t > 0 \end{cases}$$

$$= \begin{cases} 0 & , t < 0 \\ t & , t > 0 \end{cases}$$

$$= \tau(t)$$

2nd method →

$$Y(s) = X_1(s) * X_2(s)$$

$$Y(s) = \frac{1}{s} \cdot \frac{1}{s} = \frac{1}{s^2}$$

$$\boxed{Y(s) = \sigma(s)}$$

* Properties of Convolution →

(1.) Commutative →

$$x_1(t) * x_2(t) = x_2(t) * x_1(t)$$

$$\int_{-\infty}^{\infty} x_1(z) \cdot x_2(t-z) dz = \int_{-\infty}^{\infty} x_2(z) x_1(t-z) dz$$

(2.) Associative →

$$x_1(t) * [x_2(t) * x_3(t)] = [x_1(t) * x_2(t)] * x_3(t)$$

(3.) Distributive →

$$x_1(t) * [x_2(t) + x_3(t)] = x_1(t) * x_2(t) + x_1(t) * x_3(t)$$

(4.) Impulse Response →

$$x(t) * \delta(t-t_1) = x(t-t_1)$$

$$\downarrow t_1=0$$

$$x(t) * \delta(t) = x(t)$$

$$\text{Eq: } (1) u(t-1) * \delta(t+2) = u[(t+2)-1] = u(t+1)$$

(5.) Derivative →

$$y(t) = x_1(t) * x_2(t)$$

$$\frac{dy(t)}{dt} = \frac{dx_1(t)}{dt} * x_2(t) + x_1(t) * \frac{dx_2(t)}{dt}$$

$$\text{Eq: Find } y(t) = ?$$

$$y(t) = \frac{d}{dt} [x(t) * u(t)]$$

Sol?

$$y(t) = \frac{d}{dt} x(t) * u(t)$$

$$= u(t) * u(t)$$

$$= \delta(t)$$

$$(OR) y(t) = x(t) * \frac{d}{dt} u(t)$$

$$= x(t) * \delta(t)$$

$$= \delta(t)$$

(6.) Step Response →

$$y(t) = x(t) * u(t) = ?$$

$$y(t) = \int_{-\infty}^t \frac{dy(t)}{dt} dt = \int_{-\infty}^t [x(t) * \frac{du(t)}{dt}] dt$$

$$\text{Eq.} \rightarrow (1) u(t) * u(t) = \int_{-\infty}^t u(t) dt = \sigma(t)$$

$$(2) \sigma(t) * u(t) = \int_{-\infty}^t \sigma(t) dt = p(t)$$

(7) Time scaling →

If $x_1(t) * x_2(t) = y(t)$ then;

$$x_1(at) * x_2(at) = \frac{1}{|a|} y(at) \quad (a \neq 0)$$

(8) Area →

If $x_1(t) * x_2(t) = y(t)$ then;

$$\text{Area } y(t) = \text{Area } x_1(t) \times \text{Area } x_2(t)$$

(9) Time delay →

$$x_1(t) * x_2(t) = y(t)$$

$$x_1[t-t_1] * x_2[t-t_2] = y[t-(t_1+t_2)]$$

$$\text{Eq.} \rightarrow (1) u(t-1) * u(t-2) = \sigma(t-3)$$

$$= (t-3) u(t-3)$$

$$(2) \sigma(t-1) * u(t+3) = p(t+2)$$

$$= \frac{(t+2)^2}{2} u(t+2)$$

(10) Duration →

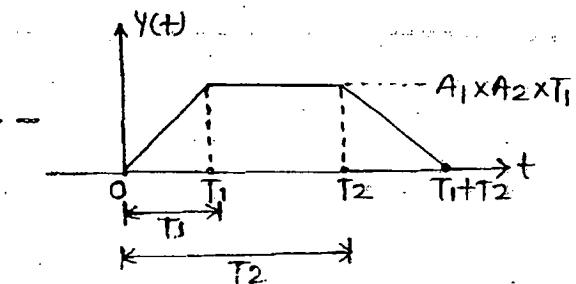
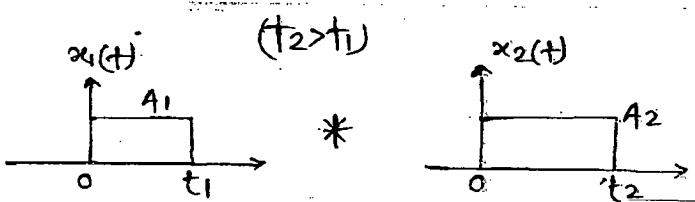
$$y(t) = x_1(t) * x_2(t)$$

Signal	Extension
$x_1(t)$	$t_1 \leq t \leq t_2$
$x_2(t)$	$t_3 \leq t \leq t_4$
$y(t)$	$t_1+t_3 \leq t \leq t_2+t_4$

* Convolution of 2 rectangular pulses of equal duration will be a triangle.

* Convolution of 2 rectangular pulses of unequal duration will be a trapezoid.

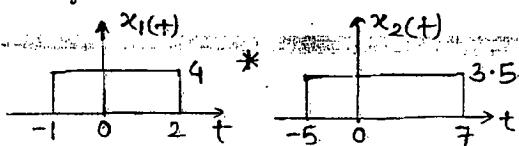
Trapezoid \rightarrow



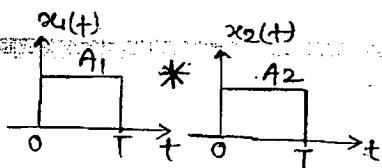
T_1 = smaller duration.

T_2 = larger duration

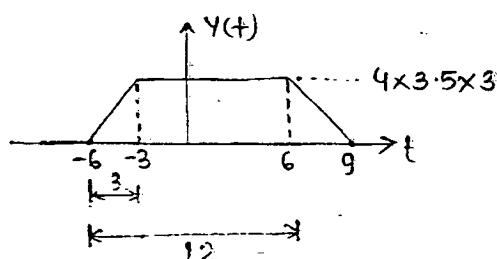
Que. \rightarrow



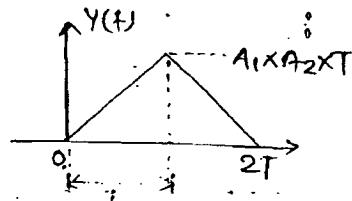
Que. \rightarrow



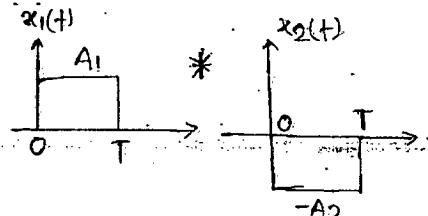
Soln \rightarrow



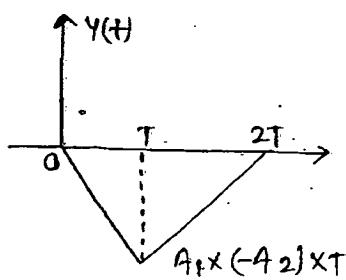
Soln \rightarrow



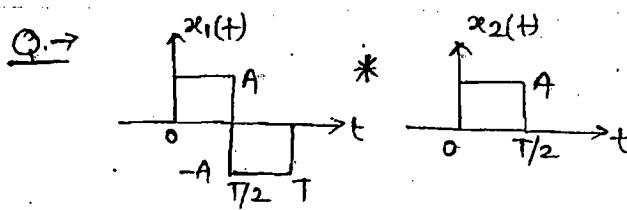
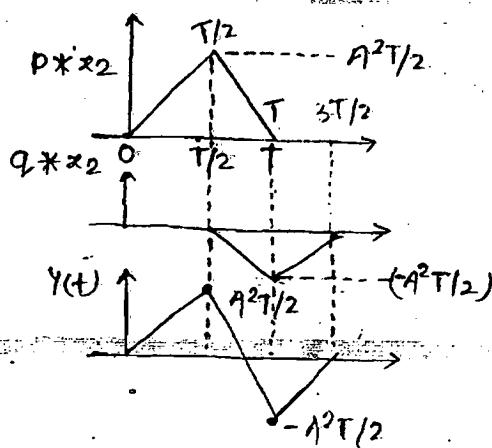
Que. \rightarrow



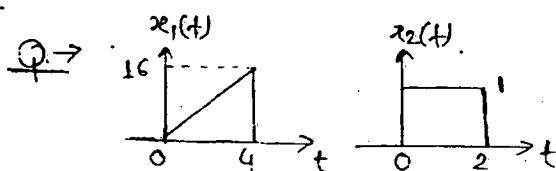
Soln \rightarrow



Because $(-A_2) \Delta$ will be -ve.

Soln

$$\begin{aligned} y(t) &= x_1(t) * x_2(t) \\ &= [P(t) + Q(t)] * x_2(t) \\ &= [P(t) * x_2(t)] + [Q(t) * x_2(t)] \end{aligned}$$



$$\begin{aligned} y(t) &= x_1(t) * x_2(t) \\ \text{Find value of } y(2) & \end{aligned}$$

(a) 4 (b) 8 (c) 16 (d) 32

Soln

$$\begin{aligned} y(t) &= x_1(t) * x_2(t) \\ &= \int_{-\infty}^{\infty} x_1(z) x_2(t-z) dz \\ y(2) &= \int_{-\infty}^{\infty} x_1(z) x_2(2-z) dz \xrightarrow{[z-2]} \int_{-\infty}^{\infty} f(z) dz \\ &= \int_{-\infty}^{\infty} f(z) dz = \text{Area of } f(z) \end{aligned}$$

where $f(z) = x_1(z) x_2(z-2)$

$\text{Area} = \frac{1}{2} \times 2 \times 8 = 8$

Area = 8

