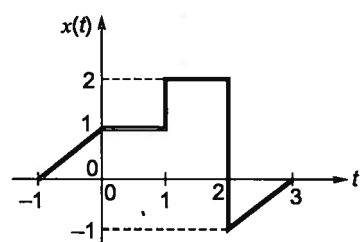


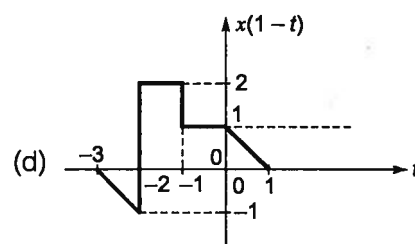
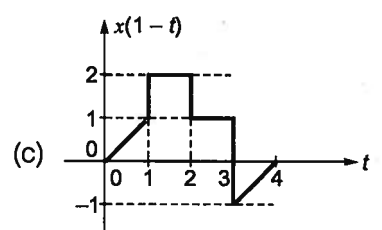
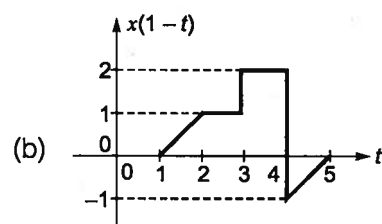
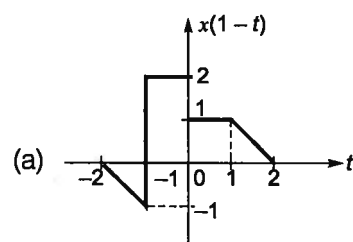


## Multiple Choice Questions

Q.1 If a plot of signal  $x(t)$  is as shown in the Figure-I,



then the plot of the signal  $x(1-t)$  will be



[ESE-1991]

Q.2 A continuous-time system is governed by the equation  $3y^3(t) + 2y^2(t) + y(t) = x^2(t) + x(t)$ .  $\{y(t)$  and  $x(t)$  respectively are output and input}. The system is

- (a) linear and dynamic
- (b) linear and non-dynamic
- (c) non-linear and dynamic
- (d) non-linear and non-dynamic

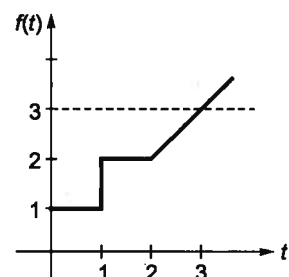
[ESE-2000]

Q.3 The signal  $x(t) = A \cos(\omega t + \phi)$  is

- (a) an energy signal
- (b) a power signal
- (c) an energy as well as a power signal
- (d) neither an energy nor a power signal

[ESE-2001]

Q.4 Consider the following waveform diagram.



Which one of the following gives the correct description of the waveform shown in the above diagram?

- (a)  $u(t) + u(t-1)$
- (b)  $u(t) + (t-1)u(t-1)$
- (c)  $u(t) + u(t-1) + (t-2)u(t-2)$
- (d)  $u(t) + (t-2)u(t-2)$

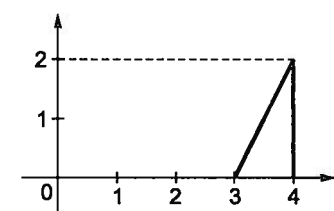
[ESE-2004]

Q.5 For half-wave (odd) symmetry, with  $T_0$  = period of  $x(t)$ , which one of the following is correct?

- (a)  $x\left(t \pm \frac{T_0}{2}\right) = -x(t)$  (b)  $x\left(t \pm \frac{T_0}{2}\right) = x(t)$
- (c)  $x(t \pm T_0) = -x(t)$  (d)  $x(t \pm T_0) = x(t)$

[ESE-2004]

Q.6 In the graph shown below, which one of the following express  $v(t)$ ?



- (a)  $(2t+6)[u(t-3) + 2u(t-4)]$
- (b)  $(-2t-6)[u(t-3) + u(t-4)]$
- (c)  $(-2t+6)[u(t-3) + u(t-4)]$
- (d)  $(2t-6)[u(t-3) - u(t-4)]$

[ESE-2005]

Q.7 Which one of the following is the correct statement? The continuous time system described by  $y(t) = x(t^2)$  is

- (a) causal, linear and time-varying
- (b) causal, non-linear and time-varying
- (c) non-causal, non-linear and time-invariant
- (d) non-causal and time-variant

[ESE-2006]

Q.8 A system with an input  $x(t)$  and output  $y(t)$  is described by the relation:  $y(t) = t x(t)$ . This system is

- (a) linear and time-invariant
- (b) linear and time varying
- (c) non-linear and time-invariant
- (d) non-linear and time-varying

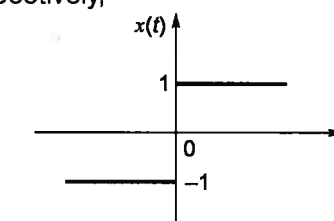
[GATE-2000]

Q.9 Convolution of  $x(t+5)$  with impulse function  $\delta(t-7)$  is equal to

- (a)  $x(t-12)$  (b)  $x(t+12)$
- (c)  $x(t-2)$  (d)  $x(t+2)$

[GATE-2002]

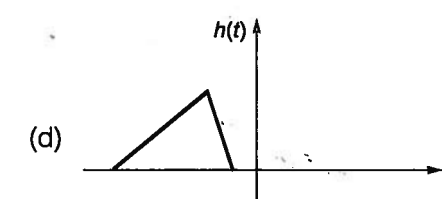
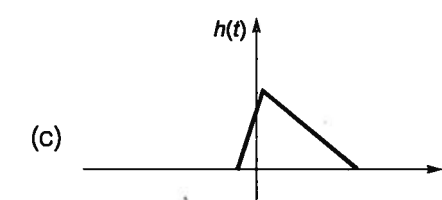
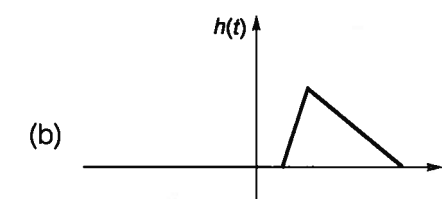
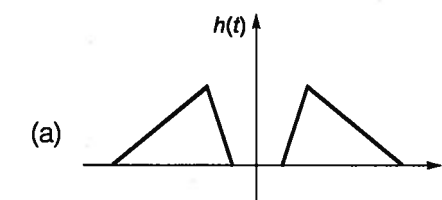
Q.10 The function  $x(t)$  is shown in the figure. Even and odd parts of a unit-step function  $u(t)$  are respectively,



- (a)  $\frac{1}{2}, \frac{1}{2}x(t)$  (b)  $-\frac{1}{2}, \frac{1}{2}x(t)$
- (c)  $\frac{1}{2}, -\frac{1}{2}x(t)$  (d)  $-\frac{1}{2}, -\frac{1}{2}x(t)$

[GATE-2005]

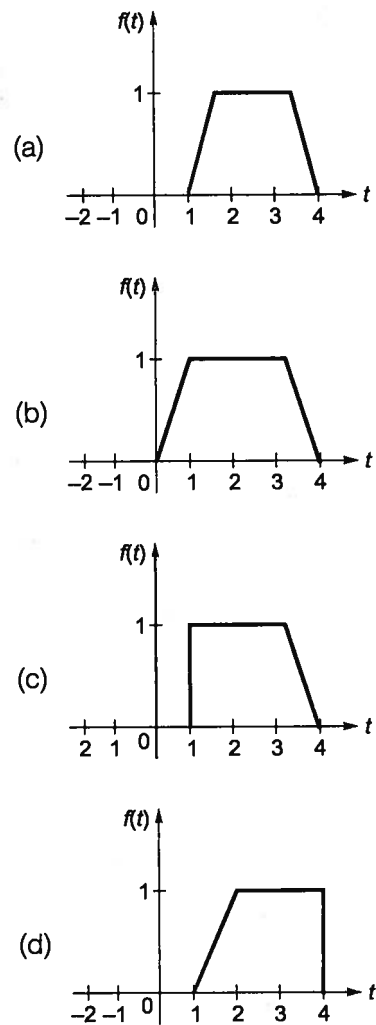
Q.11 Which of the following can be impulse response of a causal system?



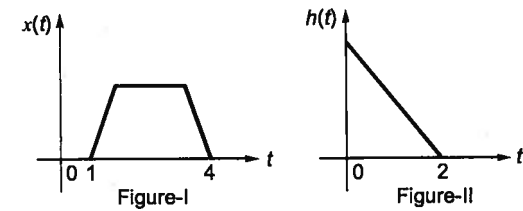
[GATE-2005]

- Q.12** Input causal signal  $t^2 + t$  is convolved with 't' (causal) to produce output  $y(t)$ . If the output for similar type signal is  $\frac{1}{3}y(3t)$  then the corresponding impulse response and input signal will be
- (a)  $3t, 3t^2 + 3t$  (b)  $3t, 9t^2 + 3t$   
(c)  $\frac{t}{3}, \frac{(9t^2 + 3t)}{3}$  (d)  $\frac{t}{3}, t^2 + t$

- Q.13** The signal  $f(t) = (t-1)u(t-1) - (t-2)u(t-2) - u(t-4)$  shows the figure below



- Q.14** Figure-I and Figure-II show respectively the input  $x(t)$  to a linear time-invariant system and the impulse response  $h(t)$  of the system.



- The output of the system is zero everywhere except for the time-interval
- (a)  $0 < t < 4$  (b)  $0 < t < 5$   
(c)  $1 < t < 5$  (d)  $1 < t < 6$

[ESE-1999]

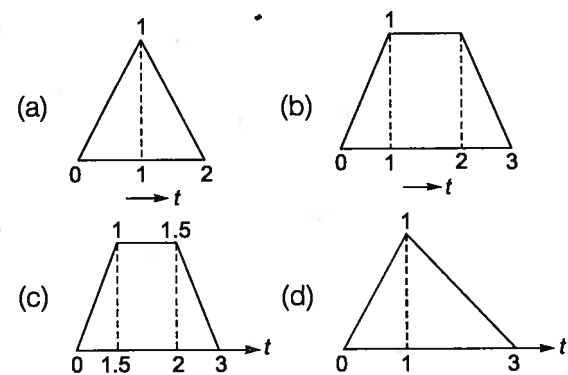
- Q.15** If a function  $f(t)u(t)$  is shifted to right side by  $t_0$ , then the function can be expressed as
- (a)  $f(t-t_0)u(t)$  (b)  $f(t)u(t-t_0)$   
(c)  $f(t-t_0)u(t-t_0)$  (d)  $f(t+t_0)u(t+t_0)$

[ESE-2001]

- Q.16** The impulse response of a system is  $h(t) = \delta(t-0.5)$ . If two such systems are cascaded, the impulse response of the overall system will be
- (a)  $0.5\delta(t-0.25)$  (b)  $\delta(t-0.25)$   
(c)  $\delta(t-1)$  (d)  $0.5\delta(t-1)$

[ESE-2001]

- Q.17** Let  $u(t)$  be the step function. Which of the waveforms in the figure corresponds to the convolution of  $u(t) - u(t-1)$  with  $u(t) - u(t-2)$ ?

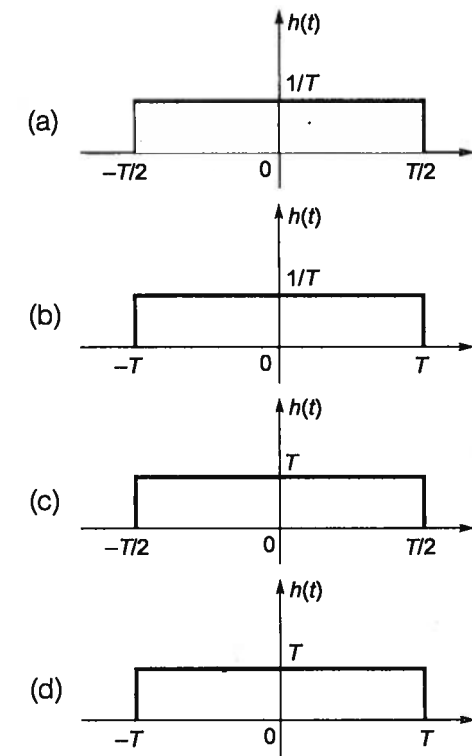


[GATE-2002]

- Q.18** A continuous time LTI is described by

$$y(t) = T\{x(t)\} = \frac{1}{T} \int_{t-T/2}^{t+T/2} x(\tau) d\tau$$

The impulse response is



- Q.19** Consider a continuous time LTI system with

$$x = \begin{cases} 1 & 0 \leq t \leq 1 \\ 0 & \text{else where} \end{cases}$$

and  $h(t) = x(t/\alpha)$  where,  $0 < \alpha \leq 1$

then output  $y(t) = x(t) * h(t)$ ;  $\alpha \leq t \leq 1$  is given by

- (a)  $1/\alpha$  (b)  $\alpha$   
(c)  $2/\alpha$  (d)  $2\alpha$

- Q.20** With the following equations, the time-invariant systems are

- $\frac{d^2y(t)}{dt^2} + 2t \frac{dy(t)}{dt} + 5y(t) = x(t)$
- $y(t) = e^{-2}x(t)$
- $y(t) = \left[ \frac{d}{dt} x(t) \right]^2$
- $y(t) = \frac{d}{dt} [e^{-2t} x(t)]$

- (a) 1 and 2 (b) 1 and 4  
(c) 2 and 3 (d) 3 and 4

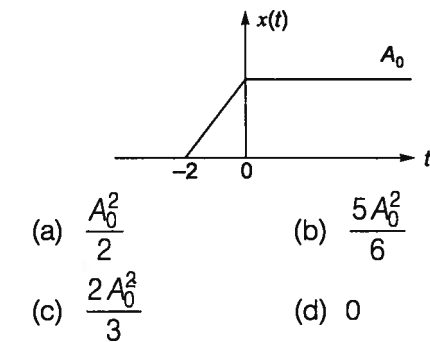
[ESE-2012]

- Q.21** Consider two signals  $x_1(t) = e^{j20t}$  and  $x_2(t) = e^{(-2+j)t}$ . Which one of the following statements is correct?

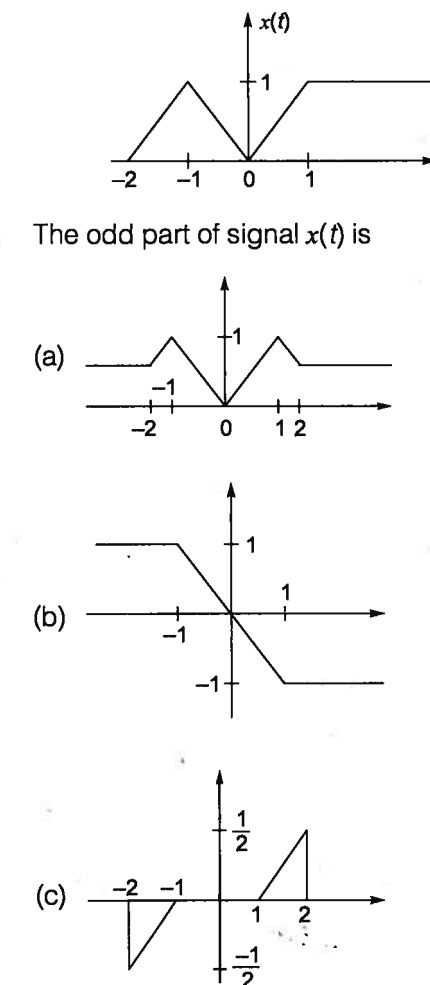
- (a) Both  $x_1(t)$  and  $x_2(t)$  are periodic  
(b)  $x_1(t)$  is periodic but  $x_2(t)$  is not periodic  
(c)  $x_2(t)$  is periodic but  $x_1(t)$  is not periodic  
(d) Neither  $x_1(t)$  nor  $x_2(t)$  is periodic

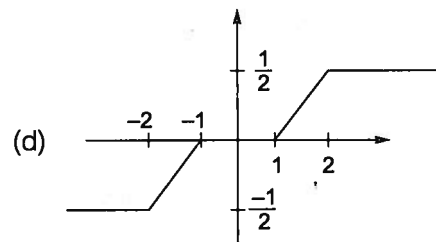
[ESE-2007]

- Q.22** The power of signal shown in the figure is:

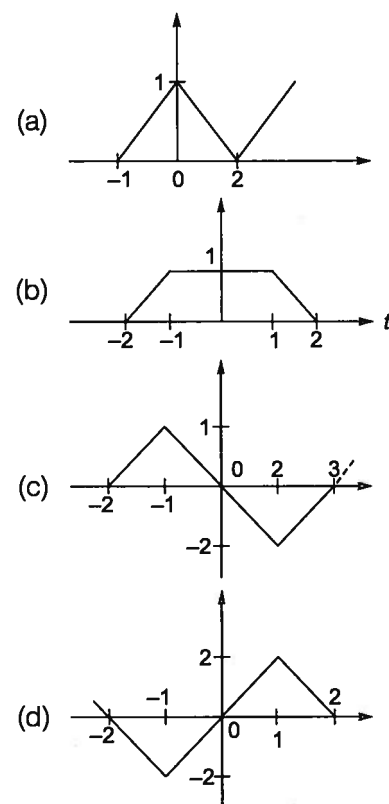


- Q.23** A signal  $x(t)$  is shown in figure below.





**Q.24** Consider a signal  $x(t)$   
 $x(t) = r(t+2) - r(t+1) - r(t-1) + r(t-2)$   
 The correct waveform of  $x(t)$



**Q.25** A continuous-time system is described by  $y(t) = e^{-|x(t)|}$ , where  $y(t)$  is the output and  $x(t)$  is the input.  $y(t)$  is bounded  
 (a) only when  $x(t)$  is bounded  
 (b) only when  $x(t)$  is non-negative  
 (c) only for  $t \leq 0$  if  $x(t)$  is bounded for  $t \geq 0$   
 (d) even when  $x(t)$  is not bounded  
**[GATE-2006]**

**Q.26** A system with  $x(t)$  and output  $y(t)$  is defined by the input-output relation:

$$Y(t) = \int_{-\infty}^{-2t} x(\tau) d\tau$$

The system will be  
 (a) Casual, time-invariant and unstable  
 (b) causal, time-invariant and stable  
 (c) non-causal, time-invariant and unstable  
 (d) non-causal, time-variant and unstable  
**[GATE-2008]**

**Q.27** The input  $x(t)$  and output  $y(t)$  of a system are related as  $y(t) = \int_{-\infty}^t x(\tau) \cos(3\tau) d\tau$ . The system is  
 (a) time-invariant and stable  
 (b) stable and not time-invariant  
 (c) time-invariant and not stable  
 (d) not time-invariant and not stable  
**[GATE-2012]**

**Q.28** Which one of the following systems is a causal system? [ $y(t)$  is output and  $u(t)$  is a input step function]  
 (a)  $y(t) = \sin(u(t+3))$   
 (b)  $y(t) = 5u(t) + 3u(t-1)$   
 (c)  $y(t) = 5u(t) + 3u(t+1)$   
 (d)  $y(t) = \sin(u(t-3)) + \sin(u(t+3))$   
**[ESE-2000]**

**Q.29** Which of the following system is linear?  
 (i).  $y(t) = tx(t)$   
 (ii).  $y(t) = tx^2(t)$   
 (iii).  $y(t) = x(2t)$   
 (a) only (i) (b) (i) and (ii)  
 (c) only (iii) (d) None

### Numerical Data Type Questions

**Q.30** The power in the signal  $s(t) = 8\cos\left(20\pi t - \frac{\pi}{2}\right) + 4\sin(15\pi t)$  is \_\_\_\_\_.  
**[GATE-2005]**

**Q.31** Consider the continuous time signal  $x(t) = \delta(t+2) - \delta(t-2)$ . The value of  $E$  for the signal  $y(t) = \int_{-\infty}^t x(\tau) d\tau$  is \_\_\_\_\_.

**Q.32** The Fourier series representations of a periodic current  $[2 + 6\sqrt{2} \cos \omega t + \sqrt{48} \sin 2\omega t]$  A. The effective value of the current is \_\_\_\_\_.  
**[ESE-2000]**

**Q.33** If a signal  $f(t)$  has energy  $E$ , the energy of the signal  $f(2t)$  is equal to \_\_\_\_\_.  
**[GATE-2002]**

**Q.34** The period of the signal  $x(t) = 10 \sin 12\pi t + 4 \cos 18\pi t$  is \_\_\_\_\_.  
**[ESE-2012]**

**Q.35**   
 $y(t) = x_1(t) * x_2(t)$   
 $y(2) = \underline{\hspace{2cm}}$

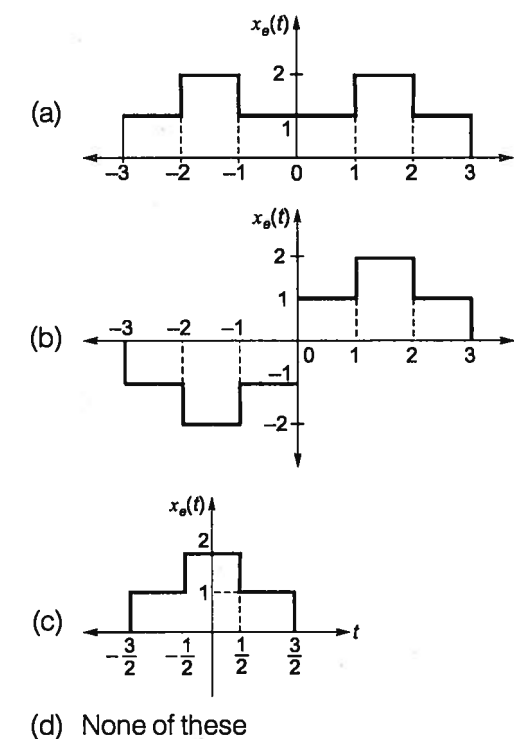
**Q.36** The rms value of the periodic waveform given in figure is \_\_\_\_\_.  
  
**[GATE-2004]**

**Q.37**   
 $y(t) = x(t) * u(t)$   
 $y(\pi/2) = \underline{\hspace{2cm}}$

**Q.38** Let  $g: [0, \infty) \rightarrow [0, \infty)$  be a function defined by  $g(x) = x - [x]$ , where  $[x]$  represents the integer part of  $x$ . (That is, it is the largest integer which is less than or equal to  $x$ ). The value of the constant term in the Fourier series expansion of  $g(x)$  is \_\_\_\_\_.  
**[GATE-2014]**

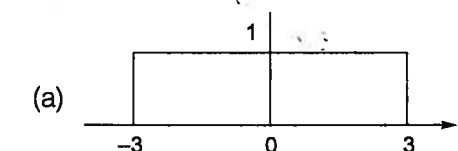
### Try Yourself

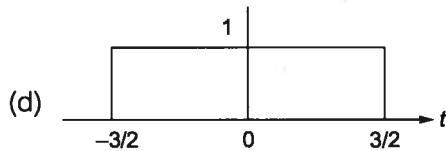
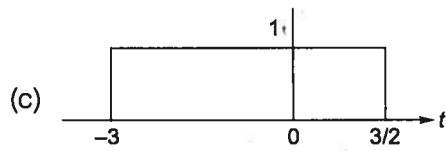
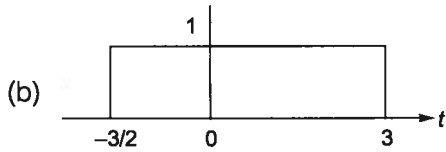
**T1.** Let  $x(t)$  be represented as shown in the figure  
  
 The even part of the signal can be represented as



**[Ans: (a)]**

**T2.** A signal  $x(t) = u(-t+5) - u(-t-4)$  is given. Sketch the signal  $y(t) = x(-2t+2)$





[Ans: (b)]

T3. Consider a continuous time signal  $x(t)$  given by

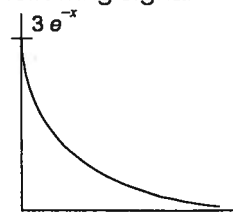
$$x(t) = \sum_{k=-\infty}^{\infty} [\delta(t - 4k) - \delta(t - 1 - 4k)]$$

The signal is

- (a) Periodic with  $T_o = 4$
- (b) Periodic with  $T_o = 3$
- (c) Periodic with  $T_o = 5$
- (d) Aperiodic

[Ans: (a)]

T4. Energy of following signal



is \_\_\_\_\_.

[Ans: (4.5)]

T5. For  $x(t) = (t-1)^2$ , value of  $\int_{-\infty}^{\infty} x(t) \delta(t-1) dt$  \_\_\_\_\_.

[Ans: (0)]

