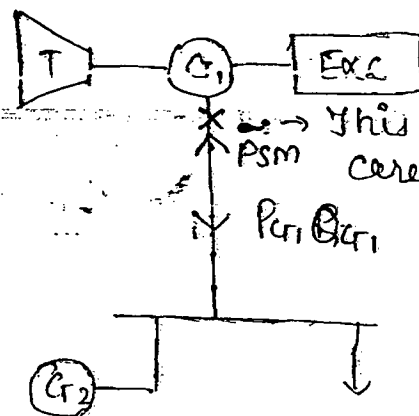


Directional or Reverse power Relay: (Wattmetrie Relay).

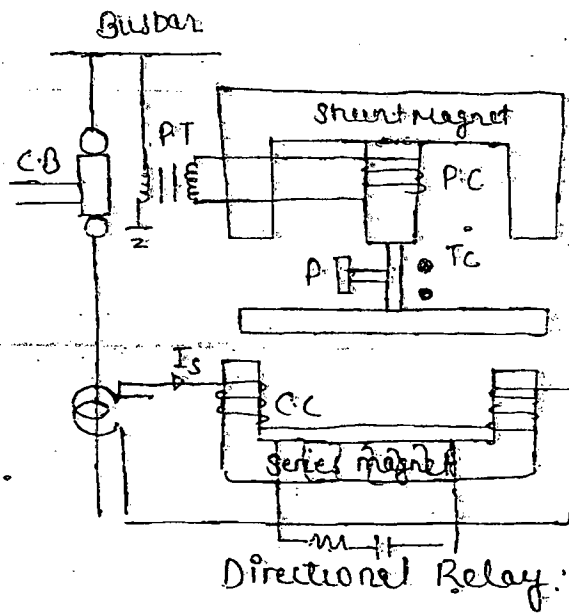
Protection of Generator from the failure of prime mover (turbine). The normal operation syn. gen. delivers both Active and reactive power. If excitation is present and prime mover is fail. then the synchronous generator working as a syn. motor. drawing the active power from other || generator (gen.). This causes temp. increment in the turbine due to churning effect which damages the turbine blades. for driving the turbine, the motor draws huge amount of current, which damages the wdg. of genr. Working as motor. for protection gen from this abnormalities relay reverse power wattmetrie Relay is used. It must have instantaneous charc. so that within short time it isolate the gen. hence it is normally made induction cup structure which has higher torque and this structure works as induction motor.



This relay is used for take care of G₁ by P_{sm}

Power from Syn. Motor

Reverse power



Non directional relay

$$T_d \propto \Phi_{m1} \Phi_{m2} \sin \theta$$

Directional relay

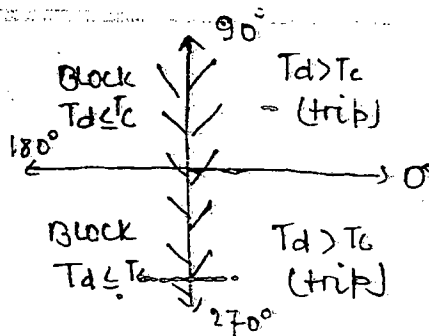
$$\Phi_{m2} \propto I_s, \Phi_{m1} \propto V$$

Angle b/w Φ_{m1} & $\Phi_{m2} \Rightarrow (90^\circ - \theta)$

$$T_d \propto VI \sin(90^\circ - \theta)$$

$$T_d \propto V I \cos \theta \propto P$$

Ideal characteristics



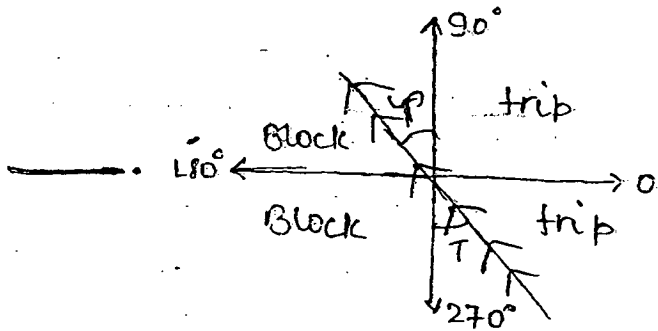
PHYSICAL

$$T_d \propto V I \cos(\theta - \gamma)$$

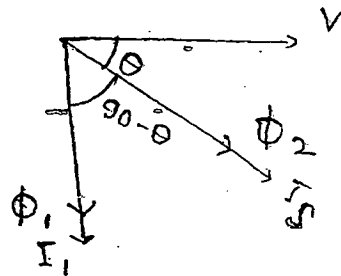
$$* \boxed{30^\circ < \gamma < 45^\circ} *$$

$T = \text{max}^m$ Torque Adjustment Angle using R.C. circuit

Practical char.



P.C. (high inductive preferred) - so produces flux ϕ_1 and C.C. produces ϕ_2 .



Initially turbine are in healthy condn. Cr. acts as synchronous generator. relay is in blocking state. but there is fault occur. Crenator and works as motor. Relay is shifted by 180° from block state to Trip state.

If $\theta = 0^\circ$ $T_d = \text{max}^m$ $T_d = VI$ it means C.C. is purely resistive. that why C.C. don't produce ϕ_2 hence we use R.C. circuit in C.C.

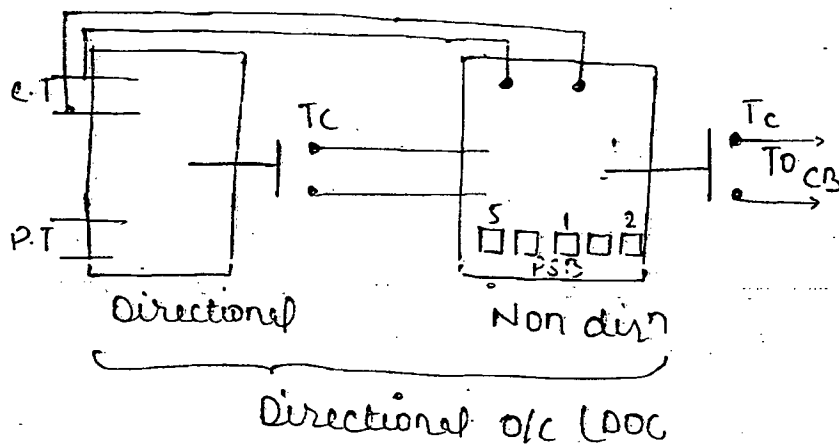
* If $\gamma \geq 45^\circ$ it work as non-direction -

Directional Overcurrent Relay:-

DOC consisting of two sub relays. One is a directional and other one is non-directional O/C relay. Which connected in cascade.

Initially Directional relay checks the dirⁿ of current and power. if the power dirⁿ is reverse produces trip signal, which initiates non dirⁿ O/C relays. This relay checks the reverse current magnitude and if this magnitude is more than PSB setting produces trip s/g which opens the C.B.

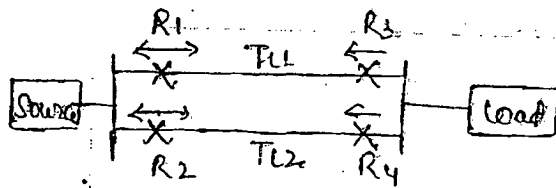
- DOC relays are used at load end and O/C/non direction relays are used at source end. the combination of O/C and D.O/C are used for protection of 11 feeders and ring trans and distribution system.



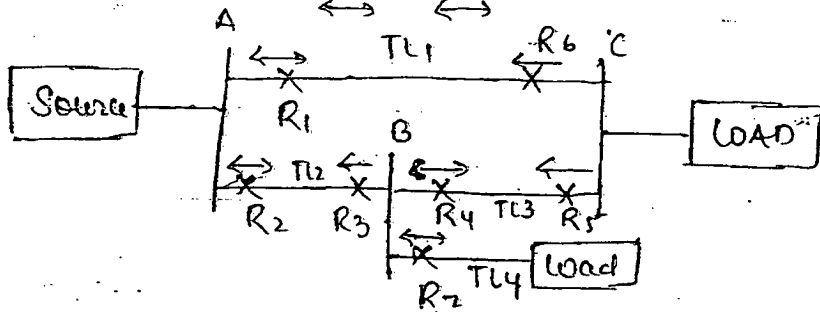
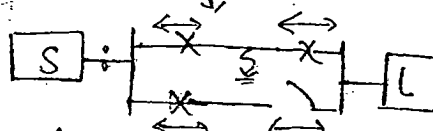
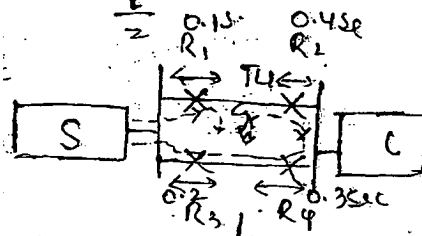
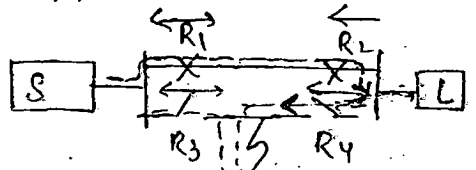
Symbol: $\xrightarrow{\quad}$ $\xleftarrow{\quad}$

Application of O/C and D/C :-

(1) Protection of 11 feeders:



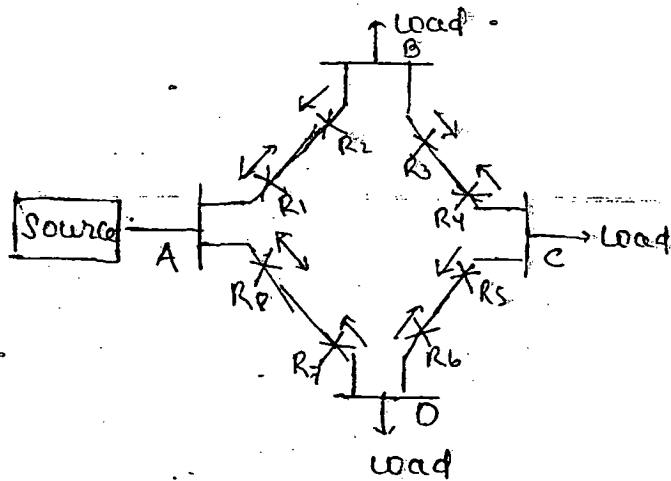
- If the fault occur in the TL2. then R_4 ~~and~~ trip first and R_2 also. If R_4 fail then R_1 operate.



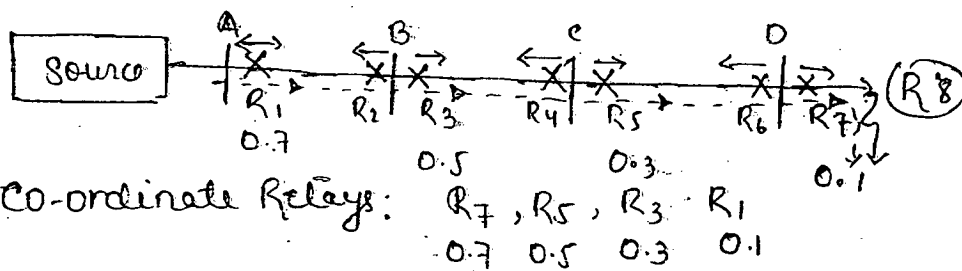
- * Protection of 11 feeder O/C relays are used at source end and D/C are used at load end. Under healthy condⁿ both the lines are feeding the power to the load. If any fault is occur in one of the line causes crossponding O/C & D/C & produces S/G and open crossponding CO. So that 50% of the power can be transmitted to the load from the

remaining healthy line.

② Protection Of Ring System.

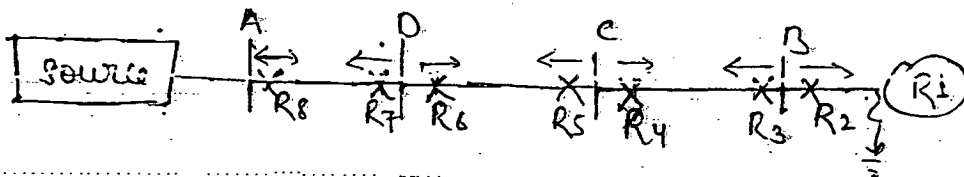


Open R_8

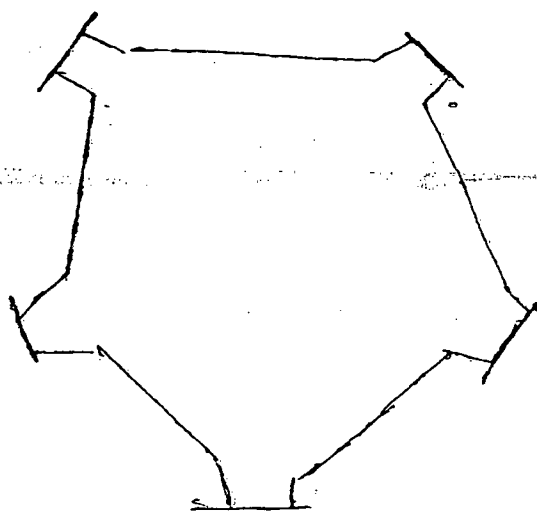
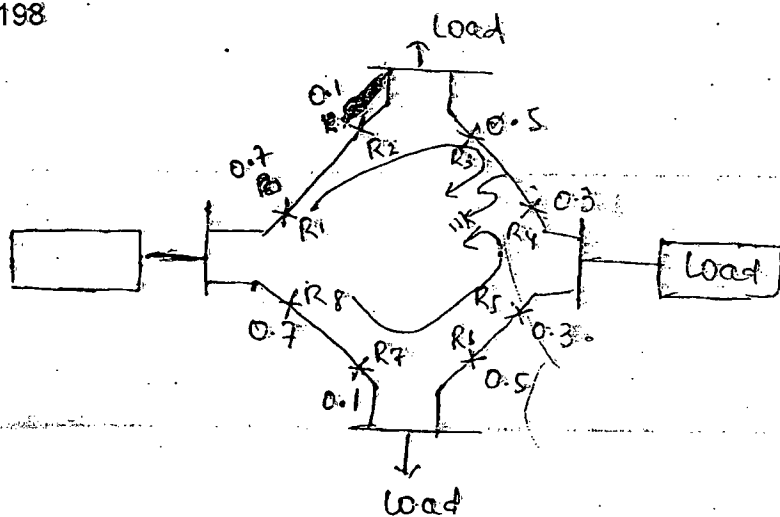


Co-ordinate Relays: R_7, R_5, R_3, R_1
 0.7 0.5 0.3 0.1

Open R_1

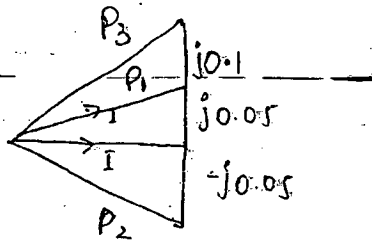


Co-ordinate Relays: R_2, R_4, R_6, R_8
 0.1 0.3 0.5 0.7



Q3. 1991

(C)



Q17 Soln:

$$Q_c = P_1 (\tan \phi_1 - \tan \phi_2)$$

$$\phi_1 = ? \quad \cos \phi_1 = 0.8 \text{ lag.}$$

18 Soln:

$$\frac{Q_2}{100} = \left(\frac{V_2}{V_1} \right)^2 \cdot \left(\frac{f_1}{f_2} \right)$$

19 Soln:

Cap bank

$$Q_{ph} = \frac{P_1 (\tan \phi_1 - \tan \phi_2)}{S(2\pi f V_{ph}^2)}$$

20 Soln:

$$Z = 8 + j6$$

$$\phi_1 = \tan^{-1}(6/8)$$

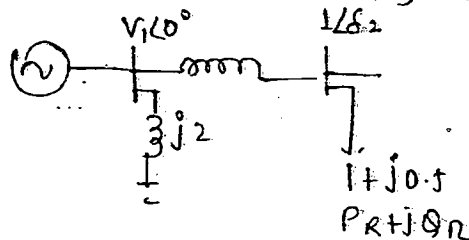
$$P = \frac{3V^2}{Z} \quad V_1 = 400$$

$$\Delta \text{ Load } P_1 = \frac{3V_1^2}{Z} \cos \phi_1$$

$$\cos \phi_1 = 0.9$$

$$Q_c = P_1 (\tan \phi_1 - \tan \phi_2)$$

35 Soln:



$$P_R = \frac{V_1 \times 1}{0.1} \sin(0.82) = 1$$

$$V_1 \sin \delta = -0.1 - \text{--- (1)}$$

$$Q_R = \frac{V_1 \times 1}{0.1} \cos(0.82) - \frac{1^2}{0.1} = 0.5$$

$$V_1 \cos \delta_2 = \text{--- (11)}$$

$$410011. 2000 \text{ IL} = V_s^2 \sqrt{\frac{C}{L}}$$

$$V_s = 800 \text{ kV}$$

$$C = 11.68 \times 10^{-9}$$

$$L = 1.1 \times 10^{-3}$$

$$\text{SIL} = 2085 \text{ MV}$$

$$42 \text{ SIL} \left[\text{SIL} / k = \frac{\text{SIL}}{\sqrt{1 - k f_e}} \right]$$

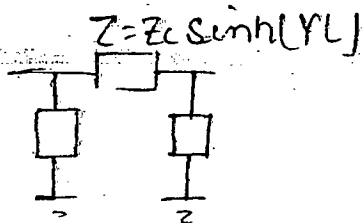
Chapter 2:

Q29.

$$L = 400 \text{ km}$$

$$Z = j0.5 / \text{km}$$

$$Y = j544 / \text{km}$$



$$Z_c = \sqrt{Z/Y} = \sqrt{\frac{0.5}{5 \times 10^{-6}}} = 316.2 \Omega$$

$$\gamma = \sqrt{ZY}$$

$$= \sqrt{0.5 \times 5 \times 10^{-6}} \times 400 = j0.632 \text{ rad} = j36.23^\circ$$

$$\sinh \gamma l \Rightarrow \sinh(\alpha l + j\beta l)$$

$$= \sinh \alpha l \cosh j\beta l + j \cosh \alpha l \sinh \beta l$$

$$= 0 + j \cosh 0 \sin(36.23^\circ) = 0.6$$

$$Z = Z_c \sinh(\gamma l)$$

$$= 316.2 \times 0.6 = 187 \Omega$$

$$\frac{V_s}{X_L} = 100 \text{ kV}$$

$$V_R = 475 \text{ kV} \rightarrow 500 \text{ kV}$$

$$Q_R = \frac{V_s V_R}{X_L} = \frac{V_R^2}{X_L}$$

$$T_4 = 20.17$$

$$P_{12} = \frac{1 \times 1}{0.05} \sin 15^\circ \Rightarrow 5.17$$

$$P_T = 15 + 5 = 20.17$$

041.201

$Z_L = \infty$

$\leftarrow 10\mu s \rightarrow$

