

* Time varying Fields, Maxwell's eqn:-

* The electric field is produced by time varying magnetic field $(\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t})$
 Produce
 Michael Faraday
 (Experimental research)

* The magnetic field is produced by time varying electric field

$$(\nabla \times \vec{E}) = \frac{\partial \vec{B}}{\partial t} \rightarrow \text{James Clerk Maxwell (Theoretical Research)}$$

Production of EM waves

$\vec{E}$ produces $\vec{H}$
 $\vec{H}$ produces $\vec{E}$

* Faraday's Law $\rightarrow$

* This law states that the time varying magnetic flux (magnetic field) produces an electromotive force (EMF) which produces a current in a closed path

Mathematically

$$\text{emf (induced)} = -\frac{d\phi}{dt}$$

minus sign is due to Lenz's law, which states that the emf induced opposes the changing magnetic flux.

$\frac{d\phi}{dt}$ is not 0 in the following cases $\rightarrow$

- (i) A stationary loop in a time varying magnetic field (xmer emf)
- (ii) A moving loop in a static magnetic field (motional emf)
- (iii) Both the cases (i.e. a moving loop in a time varying magnetic field)
 (xmer + motional emf)

* Maxwell's Equations $\rightarrow$ (derivation not required)

(1) Faraday's law $\rightarrow$

$$\text{emf} = -\frac{\partial \phi}{\partial t} \quad \text{--- (i)}$$

$$\text{emf} = \oint \vec{E} \cdot d\vec{l} \quad \text{--- (ii)} \quad \left\{ \begin{array}{l} v(t) = -\oint \vec{E} \cdot d\vec{l} \\ \text{emf is opposite of } v(t) \end{array} \right\}$$

$$\text{By definition } \phi = \iint \vec{B} \cdot d\vec{s} \quad \text{--- (iii)}$$

From (i), (iii) in (ii)

$$\oint \vec{E} \cdot d\vec{l} = -\frac{\partial}{\partial t} \iint \vec{B} \cdot d\vec{s} \quad \text{--- (iv)}$$

By Stokes theorem

$$-\oint \vec{E} \cdot d\vec{l} = \iint (\nabla \times \vec{E}) \cdot d\vec{s} \quad \text{--- (v)}$$

From (v) in (iv)

$$\iint (\nabla \times \vec{E}) \cdot d\vec{s} = \iint \left(-\frac{\partial \vec{B}}{\partial t} \right) \cdot d\vec{s}$$

Compare both side

$$\boxed{\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}} \quad \text{differential form of Maxwell eqn (v)}$$

(2) Ampere circuital law $\rightarrow$

$$\oint \vec{H} \cdot d\vec{l} = I_{\text{enclosed}} = I$$

$$\nabla \times \vec{H} = \vec{J} \quad \text{--- (i)}$$

Eqn (i) do not satisfy the continuity eqn, so Maxwell introduced $\frac{\partial \vec{D}}{\partial t}$

$$\boxed{\nabla \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t}}$$

where; $\vec{J} = \sigma \vec{E} = \frac{I_c}{\text{area}} = \text{conduction current density} = \vec{J}_c$

$$\frac{\partial \vec{D}}{\partial t} = \frac{I_d}{\text{area}} = \frac{d\psi}{dt} = \vec{J}_d = \text{displacement current density}$$

So total current density in any material

$$\vec{J}_t = \vec{J}_c + \vec{J}_d$$

(In a cond^r $\vec{J}_d \rightarrow 0$, because no electric dipole)

(In a dielectric $\vec{J}_c \rightarrow 0$, because $\vec{J}_c = nq\vec{u}$

$\therefore n \neq 0$ free $e^- = 0$)

Note → Maxwell eqⁿ:-

Law

integral form (∫)

(1) Faraday's law $\oint \vec{E} \cdot d\vec{l} = \iint \left(\frac{-\partial \vec{B}}{\partial t} \right) \cdot d\vec{s}$

(2) Ampere Circuital $\oint \vec{H} \cdot d\vec{l} = I + \iint \left(\frac{\partial \vec{D}}{\partial t} \right) \cdot d\vec{s}$

(3) Gauss law of magnetic field $\iint \vec{B} \cdot d\vec{s} = 0$

(4) Gauss law of electric field $\iint \vec{E} \cdot d\vec{s} = \frac{Q}{\epsilon_0}$

differential form (∇)

$$\vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$$

$$\vec{\nabla} \times \vec{H} = \vec{J} + \frac{\partial \vec{D}}{\partial t}$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$