

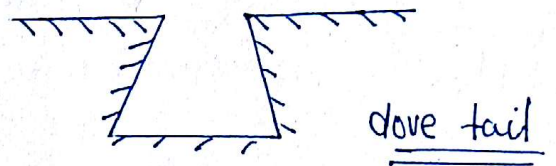
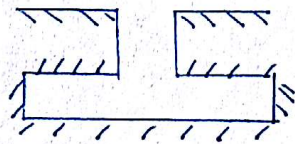
Milling

2

* In any machining operation direction of cutting is Generatrix and Direction of feed Directrix.

* In shaper and ^{planer} ~~pinner~~ both Generatrix & Directrix are ~~same~~ _{straight line}, but in turning operation Generatrix circle and Directrix is straight line.

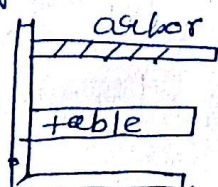
① Vertic milling Machine:



These were the initial machine developed it is also called fixed bed type machine. ~~Both~~ Motions are possible only along one plane.

② Column & knee type Machine:- It is a $2\frac{1}{2}$ axis machine

In this type of milling machine table is mounted on to knee of the milling machine. it is a $2\frac{1}{2}$ axis machine i.e. Contour can be cut in both in Horizontal and vertical plane and simultaneously feed can be given in vertical direction



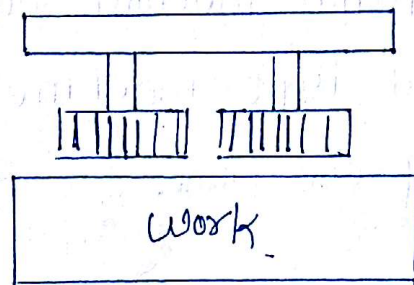
linear interp = $\frac{1}{2}$ axis
Contouring = 1 axis

③ vertically adjust (universal milling $< 45^\circ$)

It is similar to column & knee type but there is a additional facility to rotate the table less than 45° either side.

④ Rotary Type! - In this type of milling machine table can be given one complete rotation and in place of arbor there will multiple spindle in which multiple cutters mounted so machining can take places different places at simultaneously.

⑤ Planomiller! -



multiple cutters are mounted with help of individual spindle by head and reciprocation action is given by table. It is made for large size work. In a planing machine cutting action is provided by bed movement and in planomiller cutting action is provided by rotation of cutter and feed is given by table movement.

Acceptance Test



Dynamic
test

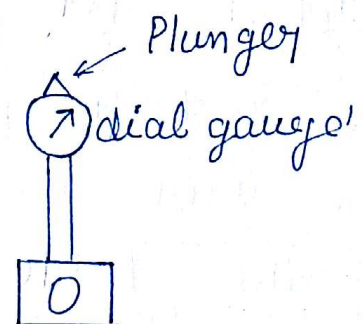
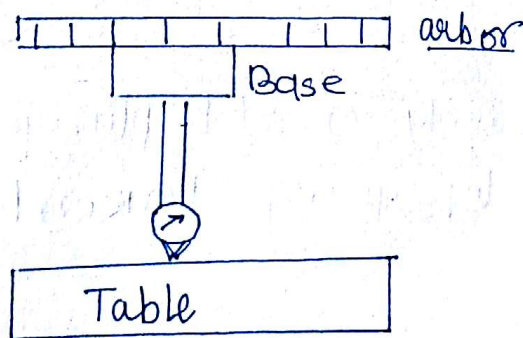
Static test
(Alignment test)

Acceptance test are performed on the new machine before adopting it to mass production.

In Dynamic test standard work pieces of free cutting steel are machine at certain speed feed and depth of cut combination and when surface & other dimension tolerance are within a certain limit machine is adopted to mass production.

Alignment or static test are performed on machine when it is stationary for a milling machine two test are very important

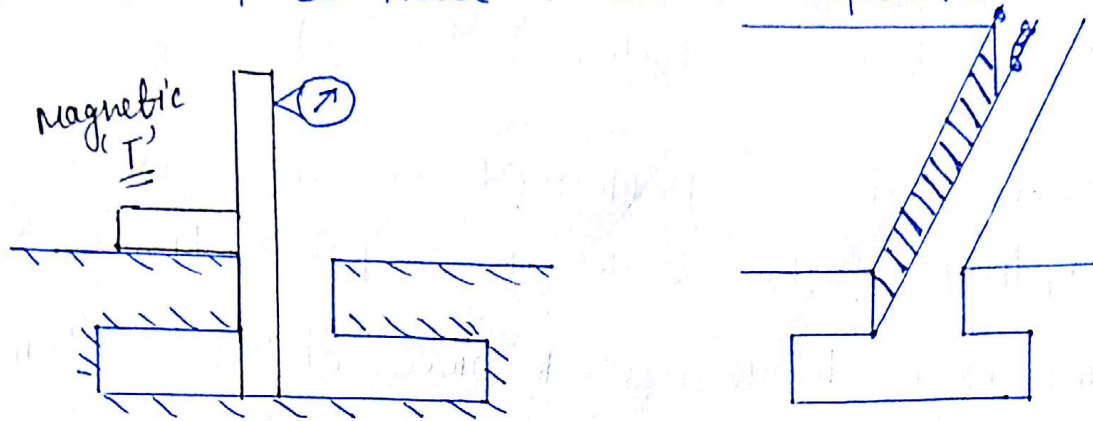
① Whether table movement parallel to arbor axis



Base of dial gauge is fixed over the arbor with plunger of dial gauge touching the table. By giving bi-axial movement to table if there is no

variation in dial gauge it mean table movement are parallel.

② Whether central T-slot is square

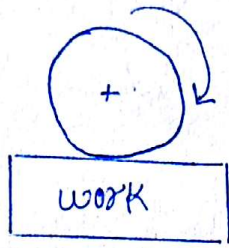


Accuracy of central T-slot is important because workpiece and other machining feature are mounted of central T-slot.

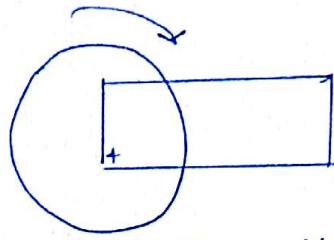
To check the $\perp$ erity of slot a magnetic 'T' is inserted in slot with plunger touching one of it's side. Base of dial gauge is fixed over arbor. By giving motion to the table if there is no variation in the dial gauge it means slot is $\perp$ er.

To check the parallelity of slot plunger move over the surface of slot by giving Horizontal motion to the table.

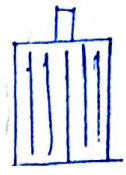
Types of milling



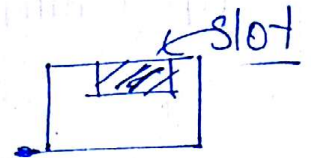
Slab/peripheral
milling



Face milling



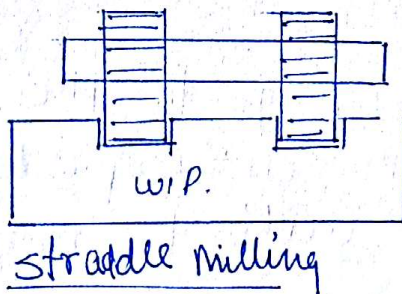
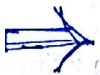
End milling



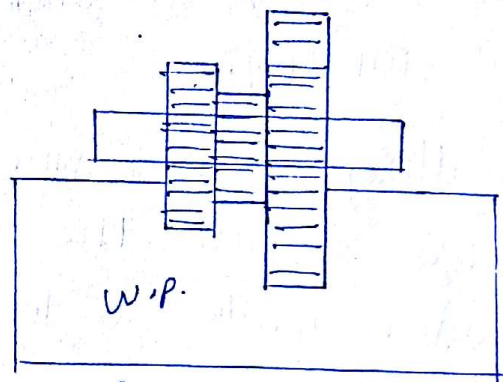
* In slab milling operation axis of rotation of cutter is parallel to the work surface

* In case of face milling operation axis of rotation of cutter will be perpendicular to work surface.

End milling is a combination of slab milling operation and it used to cut slot.



straddle milling



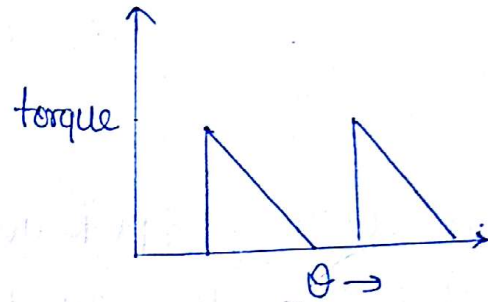
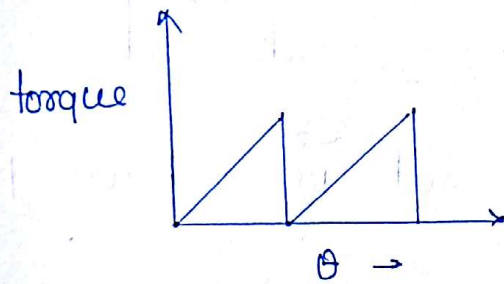
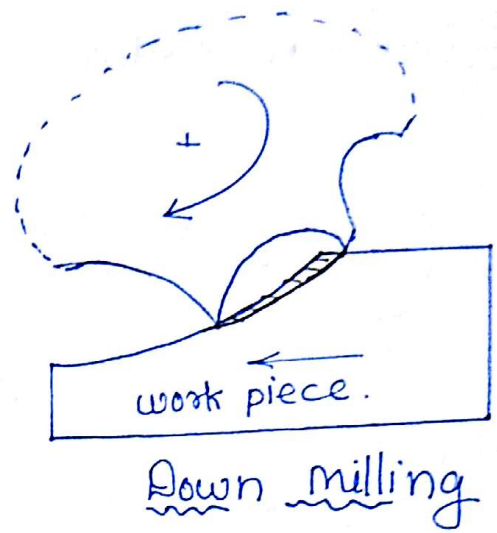
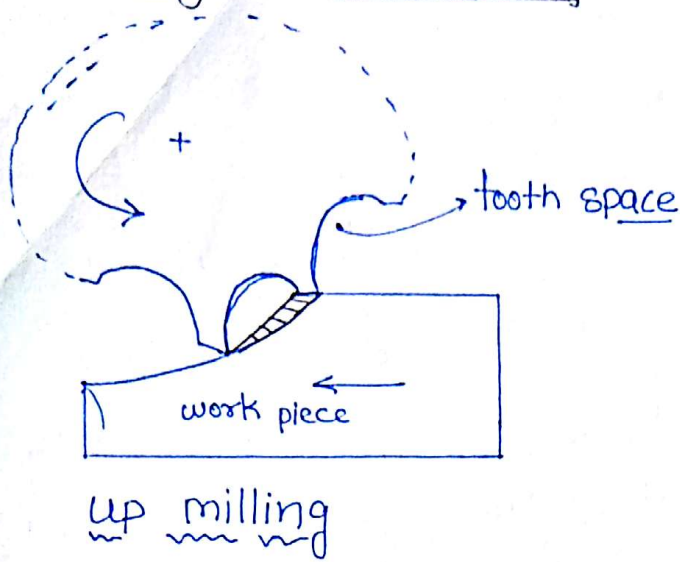
Gang milling

* when the machining taking place on work at to different places simultaneously it is called straddle milling.

* When the no. of cutter are more than two it is called a gang milling

up milling & Down milling

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- In up milling process direction of motion of cutter and workpiece is opposite. and In case of down milling it is in same direction.
- In up milling process min. chip thickness is at beginning at max. at end and opposite will be case in down milling.
- In up milling process since hot chip go to the the tooth space so due the diffusion cutting edge will become weak. so tool life will be more in down milling.
- In up milling process cutting edge is rubbing over the finish part before starting the cutting action so this will spoil the surface finish. Surface finish is better in down milling.

- In up milling since the workpiece is pulled against the table so faster will be under tension. In tension backlash error will not have any effect so accuracy will be better in up milling.

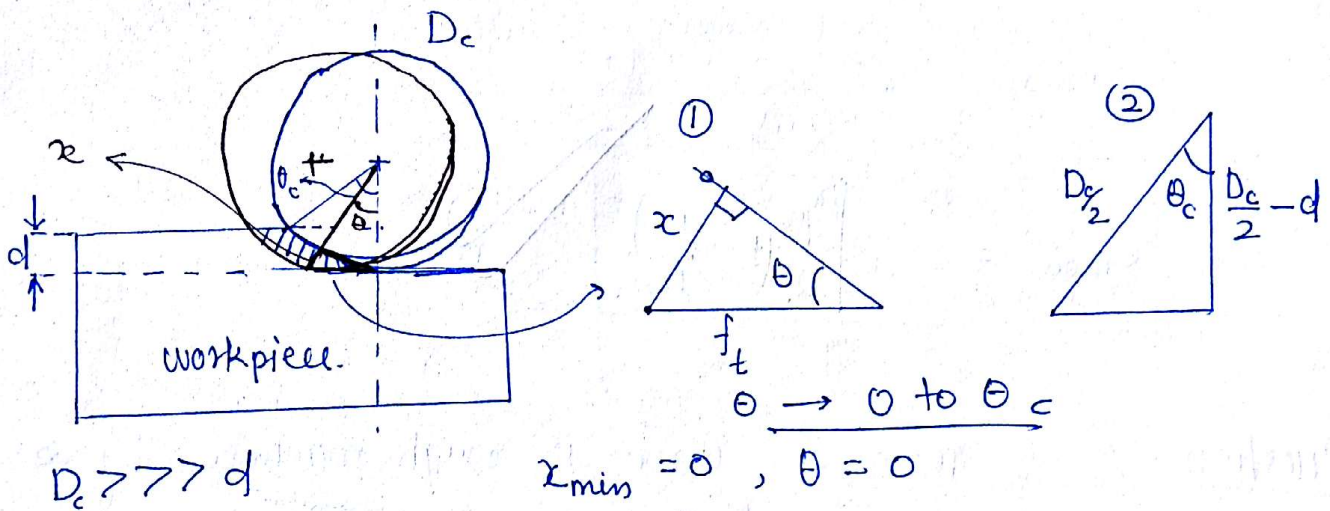
*

Uncut chip thickness

$$t_1 \propto \text{Feed/tooth}$$

$$\text{milling feed} = \text{mm/rev.}$$

$$t_1 = \frac{f}{n_t} \leftarrow \text{no of teeth.}$$



$$x_{\min} = 0, \theta = 0$$

$\theta_c = \text{contact angle}$

$$\theta \rightarrow 0 \text{ to } \theta_c$$

$\Rightarrow x_{\max} \text{ at } \theta = \theta_c$

from $\Delta 1$

$$x = f_t \sin \theta$$

from $\Delta 2$

$$\cos \theta_c = \frac{D_c/2 - d}{D_c/2}$$

$$\cos \theta_c = 1 - \frac{2d}{D_c}$$

$$\sin \theta = \sqrt{1 - \cos^2 \theta}$$

$$\sin \theta_c = \sqrt{1 - \left(1 - \frac{2d}{D_c}\right)^2}$$

$$\sin \theta_c = 2 \sqrt{\frac{d}{D_c} \left(1 - \frac{d}{D_c}\right)}$$

So $x = f_t \sin \theta$

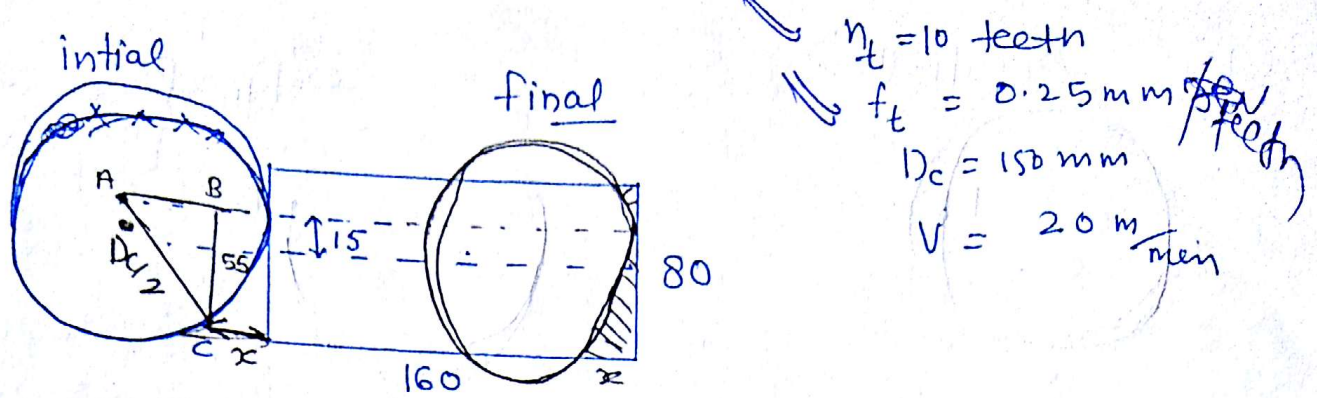
$$\boxed{x_{\max} = 2f_t \sqrt{\frac{d}{D_c} \left(1 - \frac{d}{D_c}\right)} \text{ at } \theta = \theta_c}$$

$$x_{\text{mean}} = \frac{0 + x_{\max}}{2}$$

$$\boxed{x_{\text{mean}} = f_t \sqrt{\frac{d}{D} \left(1 - \frac{d}{D}\right)}}$$

Question A 80 x 160 mm surface is rough machine by @ using a face milling cutter of 150 mm diameter having 10 teeth. The cutter center is offset by 15 mm from the line of symmetry of work piece

- (i) estimate the time to rough the surface if
feed = 0.25 mm cutting speed 20 m/min
- (ii) with 5 mm approach^{5mm} over run what is the single pass feed time
- (iii) If cutter is symmetric what is rough and finish time.



$$\text{length of cut} = 160 + x$$

$$D_c = 150 \text{ mm}$$

from $\triangle ABC$

$$AB = \sqrt{\left(\frac{D_c}{2}\right)^2 - (55)^2}$$

$$AB = 50.99$$

$$AB \approx 51 \text{ mm}$$

$$x = 75 - 51 = 24 \text{ mm}$$

$$\text{So length of cut} = 160 + 24$$

$$L_c = 184 \text{ mm}$$

$$f_t = 0.25 \text{ mm}$$

$$\text{Feed} = 0.25 \times 10 = 2.5 \text{ mm/rev.}$$

$$\text{total no. of rev in cutting} = \frac{184}{2.5} \text{ rev.}$$

$$= 73.6 \text{ rev.}$$

$$V = \pi D N$$

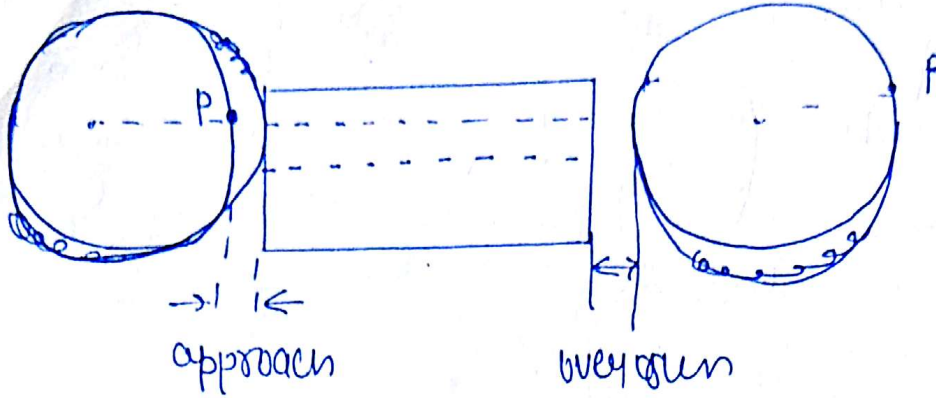
$$20 \text{ m/min} = \pi \times \frac{150}{1000} \times N \Rightarrow N = 42.4413 \text{ rpm}$$

$$\text{Time} = \frac{\text{No. of rev.}}{N} = \frac{73.6}{42.4413} = 1.734 \text{ min}$$

Cii)

initial

final



So total length of cut.

$$l = 5 + 160 + 5 + 150$$

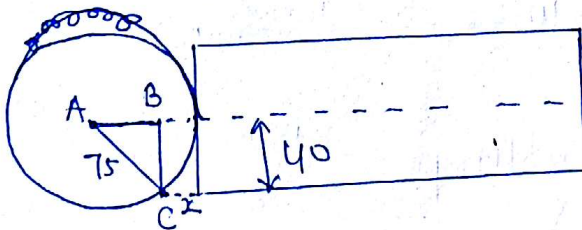
$$l = 320 \text{ mm}$$

$$\text{No. of rev.} = \frac{320}{2.5} = 128 \text{ rev.}$$

$$T_{m_2} = \frac{128}{42.44}$$

$$T_{m_2} = 3.01 \text{ min}$$

(iii)



$$AB = \sqrt{(75)^2 - (40)^2}$$

$$AB = 63.44 \text{ mm}$$

$$x = 11.55 \text{ mm}$$

$$l_c = 160 + 11.55 \text{ mm}$$

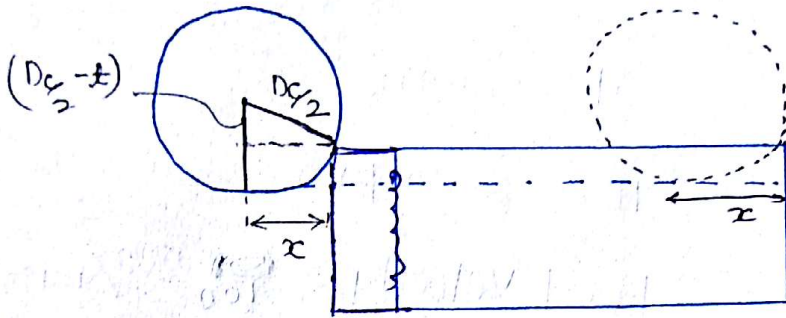
$$l_c = 171.5571 \text{ mm}$$

$$\text{No. of rev.} = \frac{171.5571}{2.5} = 68.62 \text{ rev}$$

$$T_{m_3} = \frac{68.62}{42.443} = 1.61 \text{ min}$$

Question

The thickness of a rectangular brass plate of length L_w and width b_w has to be reduced by t mm by a helical fluted slab milling cutter of length L_c ($L_c > b_w$). Cutter diameter is D_c . No. of teeth are Z_c . Cutting Velocity = V_c and $S_o = \text{feed/tooth}$. Calculate machining time.



$L_c > b_w$
width = b_w

$$x = \sqrt{\left(\frac{D_c}{2}\right)^2 - \left(\frac{D_c}{2} - t\right)^2} = \sqrt{D_c t - t^2}$$

length of cut = $L_w + \sqrt{t(D_c - t)}$

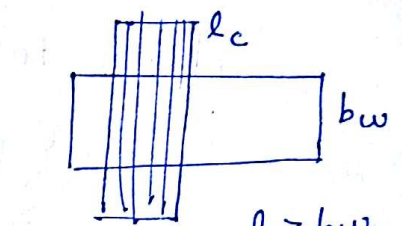
Feed = $Z_c S_o$ mm/rev.

$$V_c = \pi D_c N$$

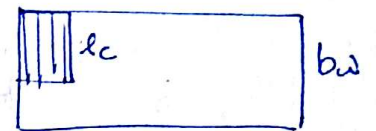
$$N = \frac{V_c}{\pi D_c}$$

$$\text{no. of rev} = \frac{L_c + \sqrt{t(D_c - t)}}{Z_c S_o}$$

$$\text{So time } T_m = \left(\frac{L_c + \sqrt{t(D_c - t)}}{Z_c S_o V_c} \right) \pi D_c$$



$L_c > b_w$
एक बार में काट देगा



$L_c < b_w$
No. of pass = $\frac{b_w}{L_c} = n$
↓
High Integer

Ans

Question Estimate the power require during milling of a mild steel block, 20 mm width using a slab milling cutter having 10 teeth, 75 mm diameter and 10° radial rake. Feed velocity = 100 mm/min . Coefficient of friction & shear strength of material are 0.5 and 400 mpa, depth of cut 5 mm & cutter rotate at 60 rpm

Solⁿ

$$W = 20 \text{ mm}$$

$$d = 5 \text{ mm}$$

$$n_t = 10$$

$$N = 60 \text{ rpm}$$

$$D_c = 75 \text{ mm}$$

$$\text{Feed velocity} = 100 \text{ mm/min.}$$

$$\mu = 0.5$$

$$\alpha = 10^\circ$$

$$\tau_s = 400 \text{ mpa}$$

$$\text{Shear force } \phi F_s = \frac{\tau_s W t_1}{\sin \phi}$$

max
chip
thickness

$$x_{\max} = 2 f_t \sqrt{\frac{d}{D} \left(1 - \frac{d}{D} \right)}$$

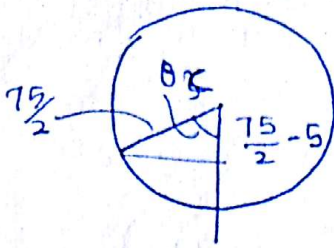
$$f_t = \frac{f}{N n_t} = \frac{100}{60 \times 10} = 0.167 \text{ mm/tooth}$$

$$x_{\max} = 2 \times \frac{1}{6} \sqrt{\frac{5}{75} \left(1 - \frac{5}{75} \right)}$$

$$x_{\max} = 0.083 \text{ mm.}$$

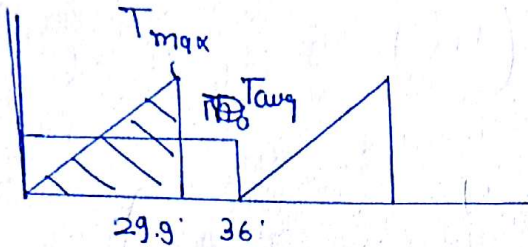
$$\alpha = 10^\circ$$

$$\text{Angle b/w 2 cutting edge} = \frac{360}{10} = 36^\circ$$



$$\cos \theta_c = \frac{(75/2 - 5)}{(75/2)}$$

$$\cos \theta_c = 29.9^\circ$$



$$\text{Power} = T_{\text{avg}} \times \omega$$

$$\frac{1}{2} \times T_{\text{max}} \times 29.9 = T_{\text{avg}} \times 36 \Rightarrow T_{\text{avg}} = \frac{T_{\text{max}}}{2.408}$$

$$T_{\text{max}} = F_s \times \frac{D}{2}$$

$$F_s = \frac{c \omega t_1}{\sin \phi}$$

less & shaffey

$$\phi + \beta - \alpha = 45^\circ$$

~~$\phi = 45^\circ$~~

$$\beta = \tan^{-1}(1/2), \alpha = 10^\circ, \phi = 28.434^\circ$$

$$\beta = \tan^{-1}(0.5) = 26.56^\circ$$

$$F_s = \frac{400 \times 20 \times 0.083}{\sin(28.431)} = 1394.487 \text{ N}$$

$$T_{\text{max}} = 1394.487 \times 37.5 = 52293 \text{ N-mm}$$

$$T_{\text{avg}} = 21716.362 \text{ N-mm}$$

$$P = T_{\text{avg}} \times \omega = T_{\text{avg}} \times \frac{\pi D N}{60}$$

$$P = \frac{21.716 \times \pi \times 75 \times 60}{60}$$

Ans $P = 184 \text{ kW}$

$$\frac{F_c}{F_s} = \frac{\cos(\beta - \alpha)}{\cos(\phi + \beta - \alpha)}$$

$$F_c = \frac{1394.487 \cos(26.56 - 10)}{\cos(45)}$$

$$F_c = 1890.303 \text{ N}$$

$$T_{\max} T_{\text{avg}} = 70.886 \text{ N-m} \quad T_{\text{avg}} = \frac{34.74}{29.43} \text{ N-m}$$

$$P = T_{\text{avg}} \times \omega$$

$$P = 29.43 \times 2\pi$$

$$P = 184 \text{ kW}$$

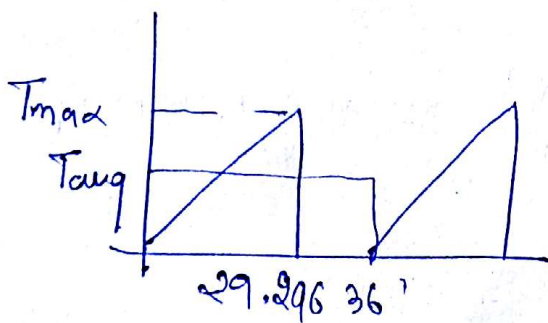
$$\omega = \frac{\pi D N}{60}$$

$$\omega = \frac{\pi \times 7.5 \times 60}{60}$$

$$\omega = 2\pi \text{ N}$$

$$\omega = 2\pi \times \frac{60}{60}$$

$$\omega = 2\pi$$



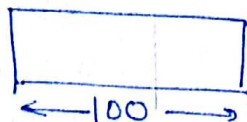
$$\frac{1}{2} \times 70.886 \times \frac{\pi}{180} = T_{\text{avg}} \times 36 \times \frac{\pi}{180}$$

$$T_{\text{avg}} = 29.43$$

$$P = 184$$

Q.3

U.B



$$l_c = 110 \text{ mm}$$

$$\text{time} = \left(\frac{110}{30} + 2 \right) \times 6$$

$$\text{Time} = 34 \text{ min}$$

$$\text{feed} = 30 \text{ mm/min}$$

$$\text{setup time} = 2 \text{ min}$$

$$\text{table travel} = 10 \text{ mm}$$

Q.6

$$V = \pi D N$$

$$N = \frac{V}{\pi D} = \frac{22 \times 10^3}{\pi \times 70} = 100.04 \text{ rpm}$$

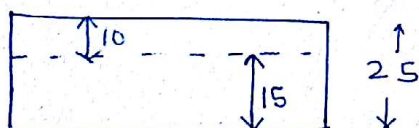
$$N = \frac{\pi D}{V} = \frac{\pi \times 70 \times 1000}{22 \times 1000} = 9.99 \times 10^{-3}$$

$$f = f_t N n$$

$$f = 0.05 \times 12 \times 100.04$$

$$f = 60 \text{ mm/min}$$

(10)

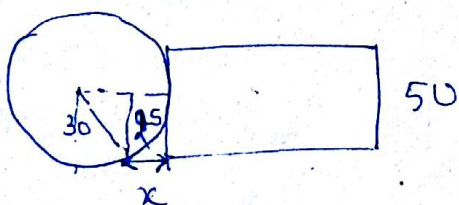


$$D = 60$$

$$n_t = 20$$

$$f_t = 0.03 \text{ mm}$$

$$N = 150 \text{ rpm}$$



$$l_c = 100 + x = 113.4168$$

$$l_c = 100 + 4.01 = 104.01$$

$$x = 30 - \sqrt{30^2 - 25^2}$$

$$x = 13.4168 \text{ mm}$$

$$\text{No. of Cuts} = \frac{104.01}{0.03 \times 20} = 5.2017335$$

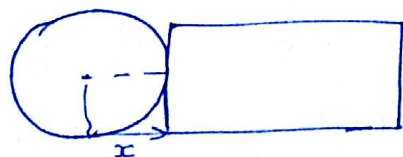
$$T_m = \frac{173.35}{150} \times 2$$

$$T_m = \frac{113.4168 \times 2}{0.03 \times 150 \times 20}$$

$$T_m = 2.52 \text{ min}$$

Q.17

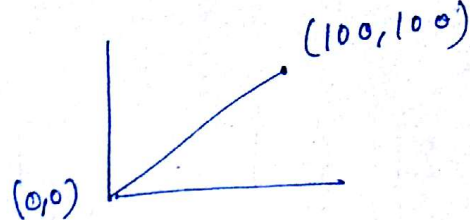
17



$$x = r$$

$$x = 5 \text{ mm}$$

$$\text{feed} = 50 \text{ mm/min}$$



$$l_c = 100\sqrt{2} \text{ mm}$$

$$l_c = (100\sqrt{2} + 5) \text{ mm} \approx$$

$$t_m = \frac{100\sqrt{2} + 5}{50} = 2.92 \text{ min}$$
$$= 175.70 \text{ sec}$$

$$(18) \quad x_{\max} = 2f_c \sqrt{\frac{d}{D}} \quad \frac{(x_{\max})_1}{(x_{\max})_2} = \frac{2f_c \sqrt{\frac{d_1}{D}}}{2f_c \sqrt{\frac{2d_1}{D}}} = 0.707$$
$$d_2 = 2d_1$$

(19)