

Chapter 10

MISCELLANEOUS THE HODOGRAPH. MOTION ON REVOLVING CURVES. IMPULSIVE TENSIONS OF STRINGS

End of Art 135 EXAMPLES

1. If P be any point on the parabola, S its focus, PK the perpendicular on the directrix, and SY the perpendicular on the tangent at P , then

$$v^2 = 2g \cdot PK = 2g \cdot SP = \frac{2g}{\alpha} \cdot SY^2.$$

Hence SY is perpendicular to, and varies as, the velocity. The hodograph is thus the locus of Y turned through a right angle, i.e. it is a vertical straight line, and it is described with uniform velocity, since the velocity in the hodograph is equal to the acceleration in the path.

2. The polar reciprocal of a conic with respect to its focus is a circle, and if the conic is a parabola this circle passes through the focus. Hence, etc., by Art. 135.

3. By Art. 46, $v = \sqrt{\mu} \cdot CD$. Hence CD is parallel and proportional to the velocity. Hence, etc.

4. $v^2 = 2g(a - a \cos \theta) = 2ga \sin^2 \frac{\theta}{2}$. Hence, etc.

5. $v = \frac{h}{SY} = \frac{h}{a + a \cos \theta}$. Hence the hodograph is the parabola $r = \frac{\lambda}{1 + \cos \theta}$ turned through a right angle about the centre of force.

6. For the hodograph; $y^2 = \lambda x$, and $\frac{dy}{dt} = V$, so that $y = Vt$ and $x = \frac{V^2}{\lambda} t^2$.

For the path; $\frac{dX}{dt} = kx = \frac{kV^2}{\lambda} t^2$, and $\frac{dY}{dt} = ky = kVt$.

$\therefore X = \frac{kV^2}{3\lambda} t^3 + A$, and $Y = \frac{kV}{2} t^2 + B$, so that $(Y - B)^2 = \frac{9k\lambda^2}{8V} (X - A)^2$.

7. With the notation of Art. 100, the figure being inverted, we have if the particle start at a depth $a - b$ below the vertex

$$v^2 = 2g[2a \cos^2 QAD - (a - b)] = 2g[a \cos 2\theta + b], \text{ where } \theta = \angle QAD.$$

If the particle starts from the highest point, then $b = a$ and $v = 2\sqrt{ga} \cos \theta$, so that the hodograph is a circle.

8. $v = \frac{h}{SY} = \frac{h}{r \sin \alpha} = \frac{h}{a \sin \alpha} e^{-\theta \cot \alpha}$. Hence the hodograph is the equi-angular spiral $r = \lambda e^{-\theta \cot \alpha}$ turned through an angle α about the pole.

9. S the pole, P any point on the curve, SY the perpendicular upon the tangent PT . Then, since

$$r^2 = a^2 \cos 2\theta, \quad \tan SPT = \frac{r d\theta}{dr} = -\cot 2\theta = \tan \left(\frac{\pi}{2} + 2\theta \right),$$

so that $\phi = \angle FSX = 3\theta$. Hence

$$v^2 = \frac{h^2}{SY^2} = \frac{h^2}{r^2 \cos^2 2\theta} = \frac{h^2}{a^2} \sec^2 \frac{2\phi}{3}.$$

Hence the hodograph is the curve $r^2 = \lambda^2 \sec^2 \frac{2}{3}\phi$ turned through a right angle, i.e. it is the curve

$$r^2 = \lambda^2 \sec^2 \left(\frac{2}{3} \cdot \frac{\pi}{2} - \phi \right) = \lambda^2 \sec^2 \frac{\pi - 2\phi}{3}.$$

10. (x, y) any point on the curve and (ξ, η) the corresponding point on the circle. Then

$$\frac{dx}{dt} = \lambda \xi = \lambda (a + a \cos \omega t), \quad \text{and} \quad \frac{dy}{dt} = \lambda \eta = \lambda a \sin \omega t.$$

$$\therefore \frac{x}{a} = \lambda t + \frac{\lambda}{\omega} \sin \omega t, \quad \text{and} \quad \frac{y}{a} = \frac{\lambda}{\omega} (1 - \cos \omega t),$$

if the particle is at the origin when $t=0$. Hence, etc.

12. $x = a \cos \theta$, $y = a \sin \theta$, and $z = a \theta \tan \alpha$, so that $z = \frac{a}{\cos \alpha} \theta$.

$$\text{Then} \quad X^2 = \lambda v^2 \left(\frac{dx}{ds} \right)^2 = \lambda \cdot 2g \sin^2 \theta \cos^2 \alpha (b - a \theta \tan \alpha),$$

$$Y^2 = \lambda v^2 \left(\frac{dy}{ds} \right)^2 = \lambda \cdot 2g \cos^2 \theta \cos^2 \alpha (b - a \theta \tan \alpha),$$

$$\text{and} \quad Z^2 = \lambda v^2 \left(\frac{dz}{ds} \right)^2 = \lambda \cdot 2g \sin^2 \alpha (b - a \theta \tan \alpha).$$

$$\therefore X^2 + Y^2 = Z^2 \cot^2 \alpha, \quad \text{and} \quad Z^2 = 2\lambda g \sin^2 \alpha \left(b - a \tan \alpha \tan^{-1} \frac{X}{Y} \right).$$

Hence, etc.

End of Art 140

EXAMPLES

1. The perpendicular OC upon the tube revolves with constant angular velocity ω , so that the acceleration of C is $\alpha\omega^2$ along CO and is zero perpendicular to CO . Hence, if $CP=r$, we have

$$\ddot{r} - r\omega^2 = 0, \text{ and } \frac{R}{m} = \alpha\omega^2 + \frac{1}{r} \frac{d}{dt} \left(r^2 \frac{d\theta}{dt} \right) = \alpha\omega^2 + 2\omega\dot{r}.$$

Hence $r = A \sinh(\omega t + B)$. Also, when $t=0$, $r=0$ and $\dot{r} = -\alpha\omega$.

$$\therefore r = -\alpha \sinh \omega t, \text{ and } \frac{R}{m} = -m\omega^2 [2 \cosh \omega t - 1].$$

2. For the motion of the particle with respect to the tube put on an extra force $m\omega^2 a \sin \theta$ outwards from the given diameter.

Then $a\ddot{\theta} = -g \sin \theta + n g \sin \theta \cos \theta$, and $a\dot{\theta}^2 = \frac{R}{m} - n g \sin^2 \theta - g \cos \theta$.

$$\therefore a\dot{\theta}^2 = 2g \cos \theta + n g \sin^2 \theta + 2g, \text{ since } \dot{\theta} = 0 \text{ when } \theta = \pi.$$

$$\begin{aligned} \therefore t \sqrt{\frac{g}{a}} &= \int_0^{\frac{\pi}{2}} \frac{\frac{1}{2} \sec^2 \frac{\theta}{2} d\theta}{\sqrt{1 + (1+n) \tan^2 \frac{\theta}{2}}} \\ &= \frac{1}{\sqrt{1+n}} \log \left[\sqrt{1+n} \tan \frac{\theta}{2} + \sqrt{1 + (1+n) \tan^2 \frac{\theta}{2}} \right]_0^{\frac{\pi}{2}} \\ &= \frac{1}{\sqrt{1+n}} \log [\sqrt{1+n} + \sqrt{2+n}]. \end{aligned}$$

3. As in Ex. 2, $a\dot{\theta}^2 = 2g \cos \theta + \omega^2 a \sin^2 \theta + B$
 $= \omega^2 a \left[2 \cos^2 \frac{\alpha}{2} \cos \theta + \sin^2 \theta - 2 \cos^2 \frac{\alpha}{2} \right], \text{ since } \dot{\theta} = 0 \text{ when } \theta = \alpha.$

$$\text{Hence } \dot{\theta}^2 = 4\omega^2 \sin^2 \frac{\theta}{2} \left(\cos^2 \frac{\theta}{2} - \cos^2 \frac{\alpha}{2} \right).$$

$$\therefore \omega t = \frac{1}{2 \sin \frac{\alpha}{2}} \int \frac{\operatorname{cosec}^2 \frac{\theta}{2} d\theta}{\sqrt{\cot^2 \frac{\theta}{2} - \cot^2 \frac{\alpha}{2}}} = -\frac{1}{\sin \frac{\alpha}{2}} \cosh^{-1} \left(\frac{\cot \frac{\theta}{2}}{\cot \frac{\alpha}{2}} \right),$$

since $\theta = \alpha$ when $t=0$. Hence, etc.

$$4. a\ddot{\theta} = \omega^2 a \sin \theta \cos \theta - g \sin \theta + \frac{\lambda}{a} \left(2a \cos \frac{\theta}{2} - a \right) \sin \frac{\theta}{2}.$$

$$\therefore a\dot{\theta}^2 = \frac{\omega^2 a}{2} (1 - \cos 2\theta) + 2(\lambda - g)(1 - \cos \theta) - 4\lambda \left(1 - \cos \frac{\theta}{2} \right). \dots (1)$$

This holds until the string becomes unstretched, i.e. until

$$\cos \frac{\theta}{2} = \frac{1}{2}, \text{ when } \theta = \frac{2\pi}{3}.$$

The motion is then given by

$$a\dot{\theta}^2 = \frac{\omega^2 a}{2} (1 - \cos 2\theta) - 2g(1 - \cos \theta) + A. \dots (2)$$

The value of $\dot{\theta}$ given by (1) and (2) must be the same when $\theta = \frac{2\pi}{3}$, so that $A = \lambda$. From (2) $\dot{\theta} = 0$ when $\theta = \pi$, if $\lambda = 4g$. Hence, etc.

5. As before the relative motion is given by

$$a\ddot{\theta} = \omega^2 a (1 - \cos \theta) \sin \theta, \text{ so that } \dot{\theta}^2 = 2\omega^2 [1 - \cos \theta] - \omega^2 \sin^2 \theta.$$

$$\therefore \omega t = \frac{1}{2} \int_{\pi}^{\pi+\phi} \frac{d\theta}{\sin^2 \frac{\theta}{2}} = \left[-\cot \frac{\theta}{2} \right]_{\pi}^{\pi+\phi} = \tan \frac{\phi}{2}. \quad \therefore \phi = 2 \tan^{-1}(\omega t).$$

6. $a\ddot{\theta} = \omega^2 a \sin \theta \cos \theta - g \sin \theta$. Hence there is relative equilibrium when $\theta=0$, or when $\cos \theta = \frac{g}{\omega^2 a}$.

First, let $\omega^2 > \frac{g}{a}$. Let $\cos \alpha = \frac{g}{\omega^2 a}$, and put $\theta = \alpha + \psi$, where ψ is small.

$$\text{Then } \ddot{\psi} = -\psi \left[\frac{g}{a} \cos \alpha - \omega^2 \cos 2\alpha \right] = -\psi \frac{\omega^2 \omega^2 a - g^2}{a^2 \omega^2}, \text{ etc.}$$

Secondly, if $\omega^2 < \frac{g}{a}$, the relative equilibrium is given by $\theta=0$.

If θ is small, then $a\ddot{\theta} = -\theta(g - \omega^2 a)$, etc.

7. $x^2 = 4ay$. The acceleration to increase x

$$= \omega^2 x \cdot \frac{x}{\sqrt{x^2 + 4y^2}} - \frac{g \cdot 2y}{\sqrt{x^2 + 4y^2}} = \frac{2ax \left(\omega^2 - \frac{g}{2a} \right)}{\sqrt{x^2 + 4y^2}}. \text{ Hence, etc.}$$

$$\begin{aligned} 8. \quad v^2 &= 3ga + 2 \int_0^y \omega^2 y \, dy - 2g(2a - x) = 3ga + \omega^2 y^2 + 2g(x - 2a) \\ &= \frac{g}{a} [y^2 + 2ax - a^2]. \end{aligned}$$

Hence $v=0$, when

$$a^3 \sin^2 \theta (1 + \cos \theta)^2 + 2a^2 \cos \theta (1 + \cos \theta) - a^2 = 0,$$

i.e. when $0 = \cos \theta [4 + 2 \cos \theta - 2 \cos^2 \theta - \cos^3 \theta] = \cos \theta (2 - \cos^2 \theta) (2 + \cos \theta)$,
the only solution of which is $\cos \theta = 0$.

$$9. \quad \frac{v^2}{\rho} = R', \text{ and } \frac{v \, dv}{ds} = 0, \text{ i.e. } v^2 = V^2. \quad \therefore R = \frac{V^2}{\rho}.$$

$$\text{Hence, by Art. 136, } R = R' + 2m\omega V = 2m\omega V + \frac{V^2}{\rho}.$$

10. At time t , let x be the stretched length of a portion of the string whose unstretched length was ξ , and T the tension at distance x . Then

$$T - (T + dT) = \omega^2 x \cdot m \, d\xi, \text{ where } \lambda \frac{dx - d\xi}{d\xi} = T.$$

$$\therefore \lambda \frac{d^2 x}{d\xi^2} = -m\omega^2 x. \quad \therefore x = A \sin \left[\sqrt{\frac{m\omega^2}{\lambda}} \xi + B \right] = A \sin \left[\frac{\theta \xi}{a} + B \right].$$

Now $x=0$ when $\xi=0$. Also $T=0$, i.e. $\frac{dx}{d\xi} = 1$, when $\xi=a$.

$$\therefore B=0 \text{ and } 1 = \frac{A\theta}{a} \cos \theta. \text{ Hence, when } \xi=a, x = A \sin \theta = \frac{a}{\theta} \tan \theta.$$

11. Here $\frac{dr}{ds} = \cos \alpha$, and $\dot{s} = \omega^2 r \cos \alpha$, i.e. $\dot{r} = \omega^2 r \cos^2 \alpha$.
 $\dot{r}^2 = \omega^2 \cos^2 \alpha (r^2 - a^2 \cos^2 \alpha)$.

For initially $\dot{s} + a\omega \sin \alpha = 0$, i.e. $\dot{r} + a\omega \sin \alpha \cos \alpha = 0$, i.e. $\dot{r} = -a\omega \sin \alpha \cos \alpha$, when $r = a$. Hence $\dot{r} = 0$ when $r = a \cos \alpha$.

Also $R' - m\omega^2 r \sin \alpha = \frac{mv^2}{\rho} = \frac{m \sin \alpha \cdot v^2}{r} = \frac{m \sin \alpha \cdot \dot{r}^2}{r \cos^2 \alpha}$.
 $\therefore R' = m\omega^2 \sin \alpha \left(2r - \frac{a^2 \cos^2 \alpha}{r} \right)$.

Hence $R = R' + 2m\omega v = R' + 2m\omega^2 \sqrt{r^2 - a^2 \cos^2 \alpha}$,
 so that, when $r = a \cos \alpha$, $R = m\omega^2 a \sin \alpha \cos \alpha$,
 and, when $r = a$, $R = m\omega^2 \sin \alpha (2a - a \cos^2 \alpha) + 2m\omega^2 a \sin \alpha = \text{etc.}$

12. Put $x + iy = Ae^{pt}$, and we obtain

$$p = \alpha + \frac{k}{2} - i(\omega - \beta), \text{ or } -\left(\alpha + \frac{k}{2} - i(\omega + \beta)\right), \text{ where } \alpha, \beta \text{ can be found.}$$

Hence if $\alpha + \frac{k}{2} = \gamma$, $\omega - \beta = \delta$, $m = -\left(\alpha + \frac{k}{2}\right)$, and $n = (\omega + \beta)$,

we have $x + iy = (A + Bi)e^{\gamma t}(\cos \delta t - i \sin \delta t) + (C + Di)e^{nt}(\cos nt - i \sin nt)$,
 so that $x = e^{\gamma t}[A \cos \delta t + B \sin \delta t] + e^{nt}[C \cos nt + D \sin nt]$,
 and $y = e^{\gamma t}[-A \sin \delta t + B \cos \delta t] + e^{nt}[-C \sin nt + D \cos nt]$.

These reduce to the given equations if we are given that, when $t=0$, then $x=1$, $y=0$, $\dot{x}=\gamma$ and $\dot{y}=-\delta$.

13. The tension of the string $= \lambda \frac{r}{a}$, so that the equations of Art. 51

become, on putting $\frac{\lambda}{dm} = \omega^2 n^2$,

$$[D^2 + \omega^2(n^2 - 1)]x - 2\omega D y = 0, \text{ and } [D^2 + \omega^2(n^2 - 1)]y + 2\omega D x = 0.$$

$$\therefore [D^2 + \omega^2(n^2 - 1)](x + iy) + 2\omega i D(x + iy) = 0.$$

Putting $x + iy = Ae^{pt}$, we have $p = \alpha i$ or $-\beta i$, where

$$\alpha = (n-1)\omega \text{ and } \beta = (n+1)\omega.$$

$$\therefore x + iy = (A + Bi)(\cos \alpha t + i \sin \alpha t) + (C + Di)(\cos \beta t - i \sin \beta t).$$

$$\therefore x = A \cos \alpha t - B \sin \alpha t + C \cos \beta t + D \sin \beta t,$$

$$\text{and } y = A \sin \alpha t + B \cos \alpha t - C \sin \beta t + D \cos \beta t.$$

Now, when $t=0$, $x=a$, $\dot{x}=0$, $y=0$ and $\dot{y}=0$.

$$\therefore \frac{A}{\beta} = \frac{C}{\alpha} = \frac{a}{\alpha + \beta}, \text{ and } B = D = 0.$$

Hence, on putting $\alpha t = \theta$, we have

$$x = \left[a - \frac{a}{2} \left(1 - \frac{1}{n} \right) \right] \cos \theta + \frac{a}{2} \left(1 - \frac{1}{n} \right) \cos \frac{n+1}{n-1} \theta,$$

$$\text{and } y = \left[a - \frac{a}{2} \left(1 - \frac{1}{n} \right) \right] \sin \theta - \frac{a}{2} \left(1 - \frac{1}{n} \right) \sin \frac{n+1}{n-1} \theta,$$

which are the equations of a hypocycloid, where the radius of the fixed circle $= a$, and that of the rolling circle

$$= \frac{a}{2} \left[1 - \frac{1}{n} \right] = \frac{a}{2} \left[1 - \omega \sqrt{\frac{dm}{\lambda}} \right].$$

14. Let A be the starting point, P any point on the tube, PM perpendicular to the vertical through A , and MN the perpendicular upon the vertical axis.

Then the acceleration $\omega^2 NP$ is equivalent to $\omega^2 NM$ and $\omega^2 MP$. Hence, if $AP=x$, we have

$$\ddot{x} = \omega^2 \cdot MP \sin \alpha - g \cos \alpha = \omega^2 \sin^3 \alpha \left[x - \frac{g \cos \alpha}{\omega^2 \sin^3 \alpha} \right].$$

$$\therefore x - \frac{g \cos \alpha}{\omega^2 \sin^3 \alpha} = A \cosh(\omega \sin \alpha t) + B \sinh(\omega \sin \alpha t).$$

Now, when $t=0$, $x=0$, and $\dot{x}=0$. $\therefore A = -\frac{g \cos \alpha}{\omega^2 \sin^3 \alpha}$, and $B=0$.

$$\therefore x = \frac{g \cos \alpha}{\omega^2 \sin^3 \alpha} [1 - \cosh(\omega \sin \alpha t)] = -\frac{g \cos \alpha}{\omega^2 \sin^3 \alpha} \sinh^2\left(\frac{1}{2} \omega \sin \alpha t\right).$$

End of Art 143

EXAMPLES

1. Equation (4) of Art. 142 gives

$$\frac{d^2 T}{d\theta^2} = T, \text{ so that } T = Ae^\theta + Be^{-\theta} = \frac{e^{\pi-\theta} - e^{-(\pi-\theta)}}{e^\pi - e^{-\pi}} \cdot T_0,$$

since $T=T_0$ when $\theta=0$, and $T=0$ when $\theta=\pi$.

2. Here $\tan \phi = r \frac{d\theta}{dr} = \frac{2}{3}$, so that $\frac{dr}{ds} = \frac{3}{\sqrt{13}}$ and $p = r \cdot \frac{2}{\sqrt{13}}$, and hence $\rho = r \frac{dr}{dp} = \frac{\sqrt{13}}{2} r$. Hence equation (4) of Art. 142 gives $\frac{d^2 T}{dr^2} = \frac{4}{9} \frac{T}{r^3}$. Putting $T=r^n$, we have $n = \frac{4}{3}$ or $-\frac{1}{3}$.

$$\therefore T = Ar^{\frac{4}{3}} + Br^{-\frac{1}{3}} = Ce^{\frac{2\theta}{3}} + De^{-\frac{\theta}{3}},$$

where

$$T_0 = C + D \text{ and } 0 = Ce^{\frac{2\pi}{3}} + De^{-\frac{\pi}{3}},$$

so that

$$\frac{C}{e^{\frac{2\pi}{3}}} = \frac{D}{e^{\frac{\pi}{3}} - 1} = \frac{T_0}{e^{\frac{2\pi}{3}} - 1}. \text{ Hence, etc.}$$

3. Here $\tan \phi = \frac{3}{8}$, $\frac{dr}{ds} = \frac{8}{\sqrt{73}}$, $p = \frac{3r}{\sqrt{73}}$ and $\rho = \frac{\sqrt{73}}{3} r$. Hence we have

$$\frac{d^2 T}{dr^2} \cdot \frac{64}{73} = \frac{T}{r^2} \cdot \frac{9}{73}.$$

Putting $T=r^n$, we have $n = \frac{9}{8}$ or $-\frac{1}{8}$, so that $T = Ar^{\frac{9}{8}} + Br^{-\frac{1}{8}}$.

But $T=2$ when $r=1$, and $T=1$ when $r=256$, so that $A=0$ and $B=2$.

Hence when $r=81$, $T = \frac{2}{\sqrt{3}} = \frac{2\sqrt{3}}{3}$.

4. Let T be the blow, per unit of length, on the upper sphere, so that

$$mV = 2\pi r \cdot T \cos \alpha = \frac{2\pi r \sqrt{R^2 - r^2}}{R} \cdot T.$$

Also, if T_1 is the impulsive tension in the wire, then

$$T_1 \cdot 2 \sin \theta = T \sin \alpha \cdot 2r\theta, \text{ where } \theta \text{ is very small.}$$

$$\therefore T_1 = r \sin \alpha T = \frac{r^2}{R} \cdot T = \frac{mVr}{2\pi \sqrt{R^2 - r^2}}.$$

5. Let AOB be the horizontal diameter, B being the point at which the vertical part of the string is tangential, and let $f (= a\ddot{\psi})$ be the acceleration of the string at time t .

Then, θ being the angular distance of any point of the string in the tube from A , we have

$$m\delta\theta \cdot f = (T + \delta T) \cos \delta\theta - T - mga \delta\theta \cos \theta = \delta T - mga \delta\theta \cos \theta.$$

$$\therefore maf(\theta - \psi) = T - mga(\sin \theta - \sin \psi), \text{ since } T=0 \text{ when } \theta=\psi.$$

Hence, if T_1 is the tension at B ,

$$maf(\pi - \psi) = T_1 + mga \sin \psi.$$

But, for the vertical portion of the string, we have

$$ma\psi \cdot f = -T_1 + mga\psi.$$

Hence $mf\pi = mg(\psi + \sin \psi)$, i.e. $a\pi\ddot{\psi} = g(\psi + \sin \psi)$.

$$\text{Also } \frac{T}{mga} = \sin \theta - \sin \psi + (\theta - \psi) \cdot \frac{\psi + \sin \psi}{\pi}.$$

The maximum value of T is given by $\frac{dT}{d\theta} = 0$, and then $\cos \theta = -\frac{\psi + \sin \psi}{\pi}$.

6. At any moment let β and γ be the vectorial angles of the ends of the chain. For any element of the chain, if f be its acceleration, we have

$$m\delta s \cdot f = (T + \delta T) \cos \delta\psi - T + m\mu r \cdot \delta s \cos \alpha = \delta T + m\mu s \cdot \delta s \cos^2 \alpha.$$

$$\therefore mfs = T + \frac{m\mu}{2} s^2 \cos^2 \alpha + A. \dots\dots\dots(1)$$

Since the tension is zero at each end, this gives

$$f \cdot l = \frac{\mu}{2} [s_\gamma^2 - s_\beta^2] \cos^2 \alpha, \text{ i.e. } f = \frac{\mu}{2} (s_\gamma + s_\beta) \cos^2 \alpha.$$

The distance of a particle at the middle point of the chain from the pole

$$= \frac{s_\gamma + s_\beta}{2} \cdot \cos \alpha, \text{ and hence its acceleration}$$

$$= \mu \left[\frac{s_\gamma + s_\beta}{2} \cos \alpha \right] \cos \alpha = \frac{\mu}{2} (s_\gamma + s_\beta) \cos^2 \alpha = f.$$

Also (1) gives

$$T + \frac{m\mu}{2} (s^2 - s_\beta^2) \cos^2 \alpha = mf(s - s_\beta) = \frac{m\mu}{2} (s_\gamma + s_\beta) (s - s_\beta) \cos^2 \alpha.$$

$$\therefore T = \frac{m\mu}{2} \cos^2 \alpha (s - s_\beta) [s_\beta + s_\gamma - (s + s_\beta)] = \frac{m\mu}{2} \cos^2 \alpha (s - s_\beta) (s_\gamma - s)$$

$$= \frac{m\mu}{2} \cdot x(l - x) \cos^2 \alpha.$$